



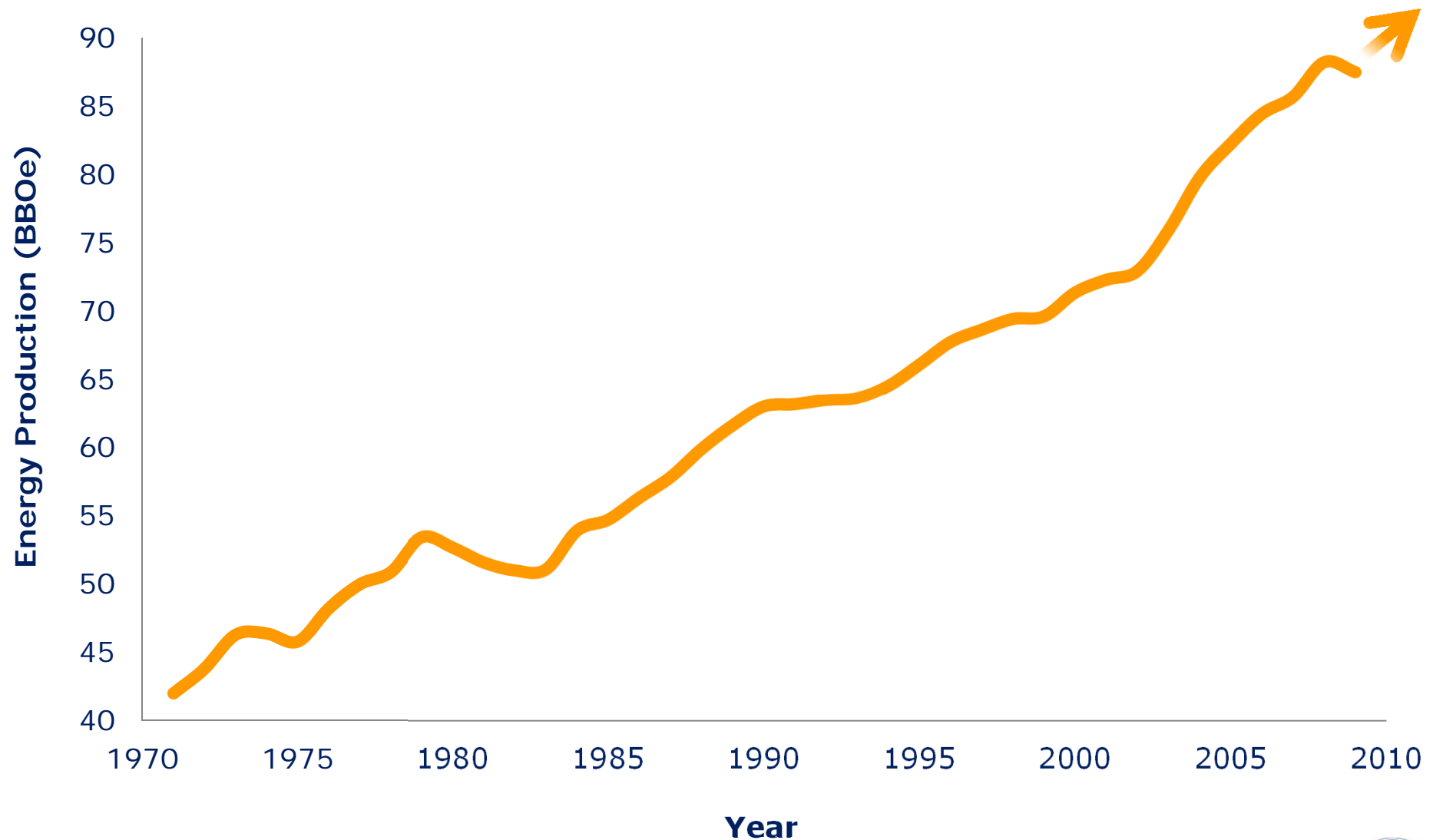
DYNAMIC OPTIMIZATION

Energy System Planning under Uncertainty

24 July 2013

Jose Mojica
Ian Greenquist
John Hedengren
Brigham Young University

Global Energy Production



Overview

- PRISM Group Overview
- Dynamic Optimization for:
 - Unmanned Aerial Vehicles
 - Systems Biology
 - Solid Oxide Fuel Cells
 - Energy Storage and the Smart Grid
 - Investment Planning Under Uncertainty
- Needs and resources for dynamic optimization

PRISM Group

- Methods
 - Mixed Integer Nonlinear Programming (MINLP)
 - Dynamic Planning and Optimization
 - Uncertain, Forecasted, Complex Systems
- Research Applications
 - Unmanned Aerial Vehicle (UAV) control
 - Systems biology and pharmacokinetics
 - Oil and gas exploration and production
 - Hybrid and sustainable energy systems

Problem Formulation

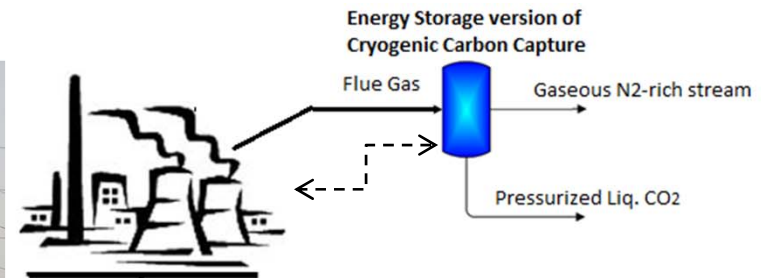
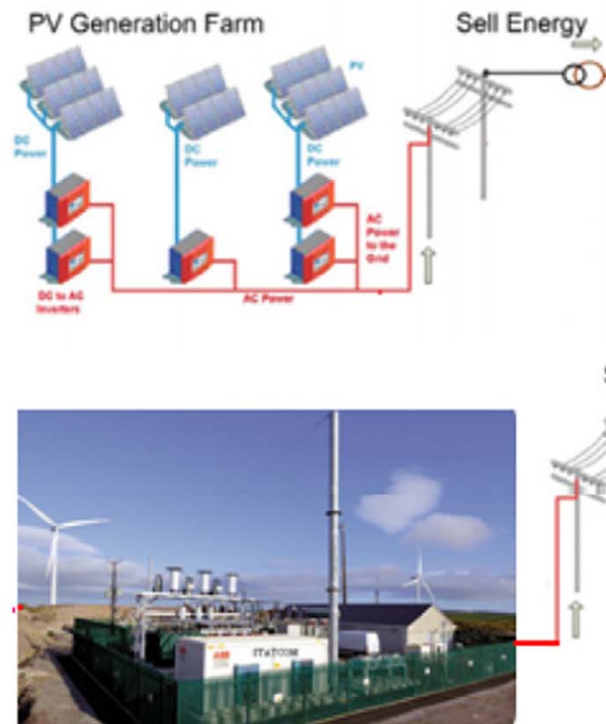
- Standard Problem Formulation

$$\begin{aligned} &\max f(x) \\ &\text{subject to } g\left(\frac{\partial x}{\partial t}, x, u, p\right) = 0 \\ &\quad h(x, u, p) \leq 0 \end{aligned}$$

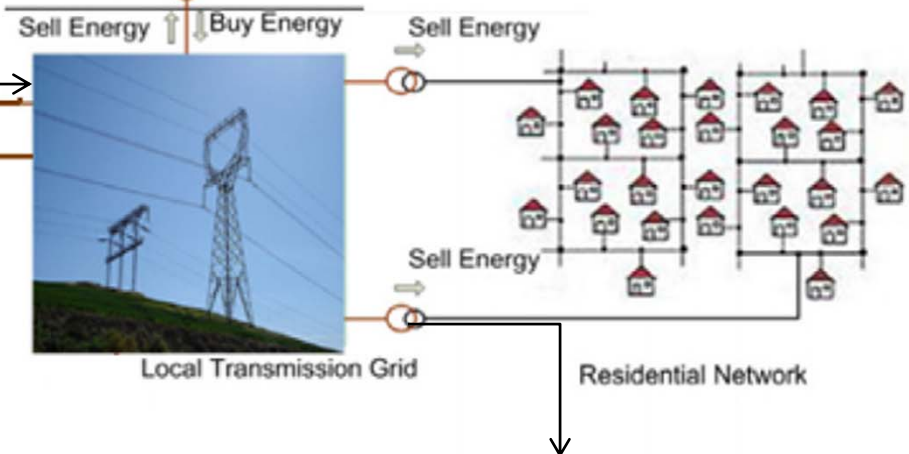
- Objective Function ($f(x)$)
- Dynamic model equations that relate trajectory constraints, sensor dynamics, and discrete decisions
- Uncertain model inputs as unmodeled or stochastic elements
- Solve large-scale MINLP problems (100,000+ variables)

Smart Grid Optimization

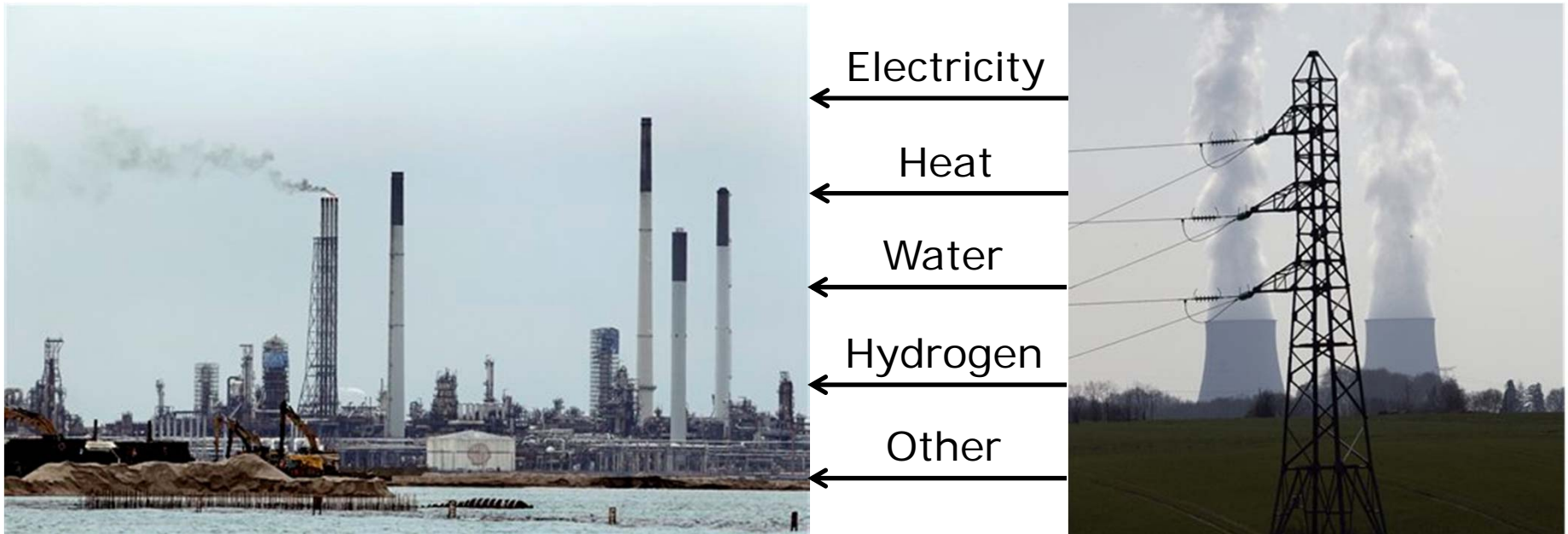
Smart grid integration with solar, wind, coal, biomass, natural gas, and energy storage



Nuclear integration with petrochemical production, processing, and distribution



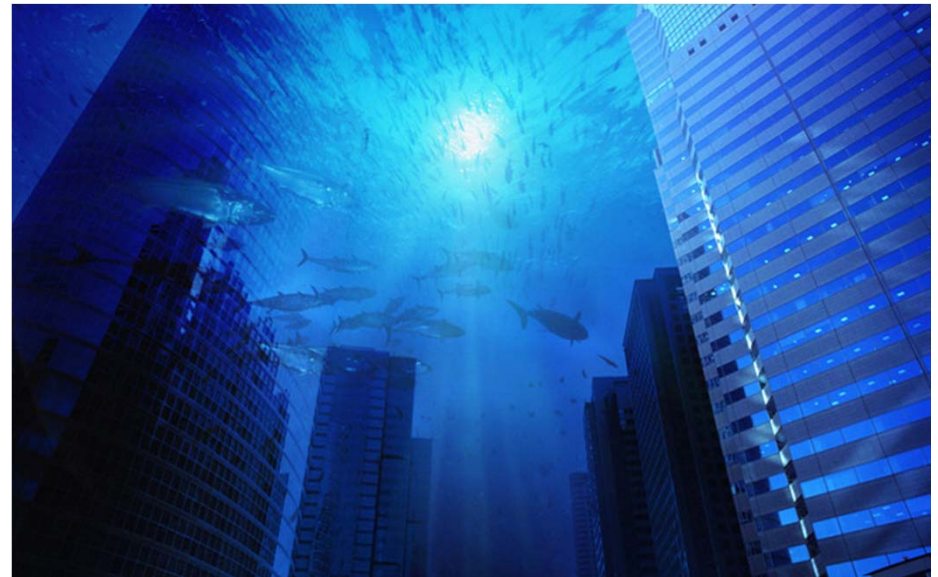
Nuclear with Petrochemical Industries



- 12% of total U.S. energy use from refining and chemicals
- \$57 billion annually on energy
- Potential refinery and nuclear integration with electricity, heat, hydrogen, and other production-consumption pairings
- Transportation fuels are 28% of U.S. energy total

Underwater Oil Rigs

- Petrobras, a Brazilian oil company, plans to use unmanned, highly automated underwater oil rigs beginning in 2020
- Nuclear reactors for:
 - Electricity
 - Heated pipe in pipe to discourage hydrate formation
 - Gas, water, oil processing



Nuclear for Water Purification

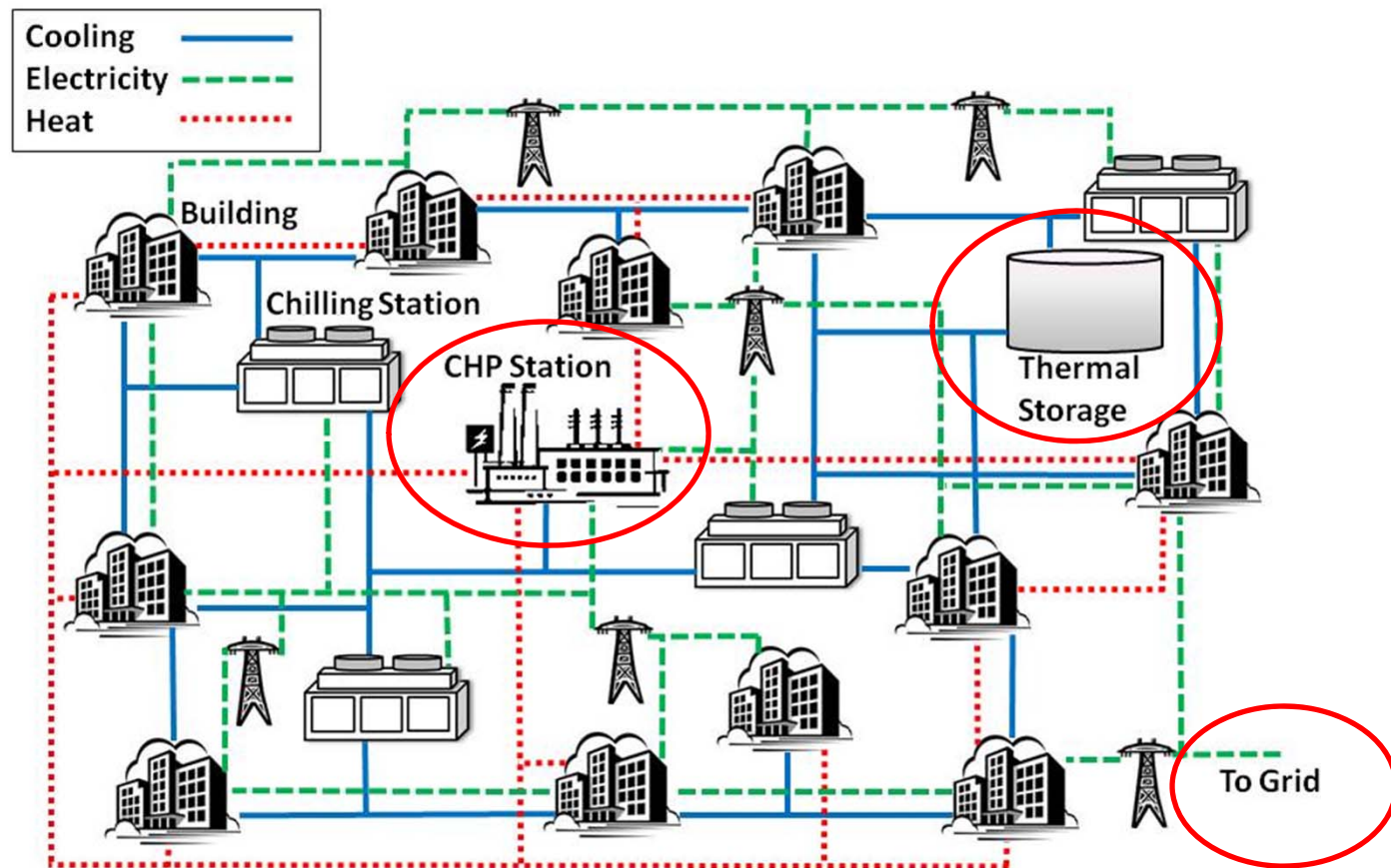
- Cooling towers purify and consume 1.05 gal/kW-hr
- Several nations have access to nuclear power, but limited amounts of renewable fresh water



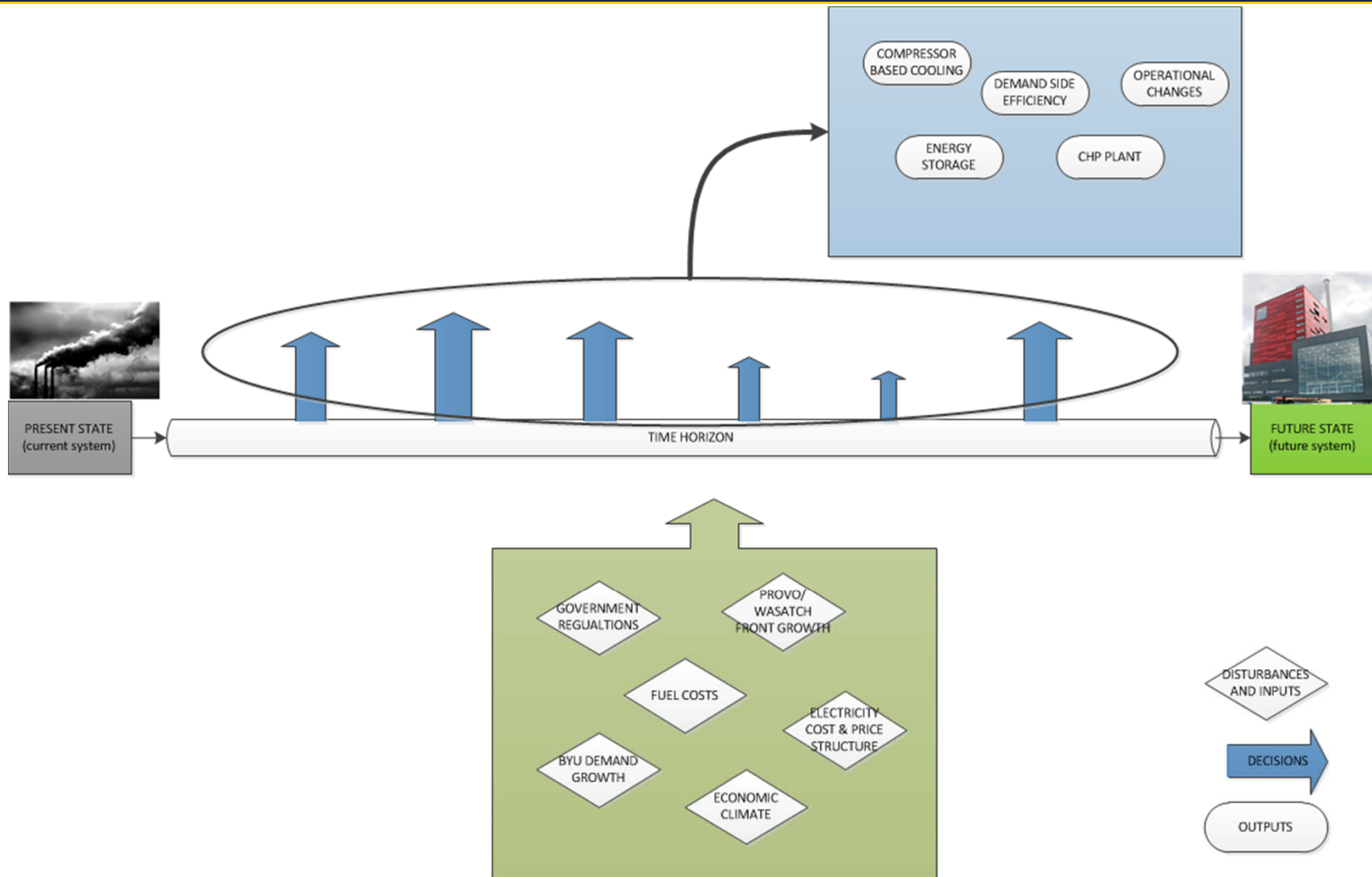
World's largest desalination facility in Saudi Arabia to produce electricity and water (July 2013)

KSA desalination consumes 300,000 barrels of oil per day at \$3.20/m³

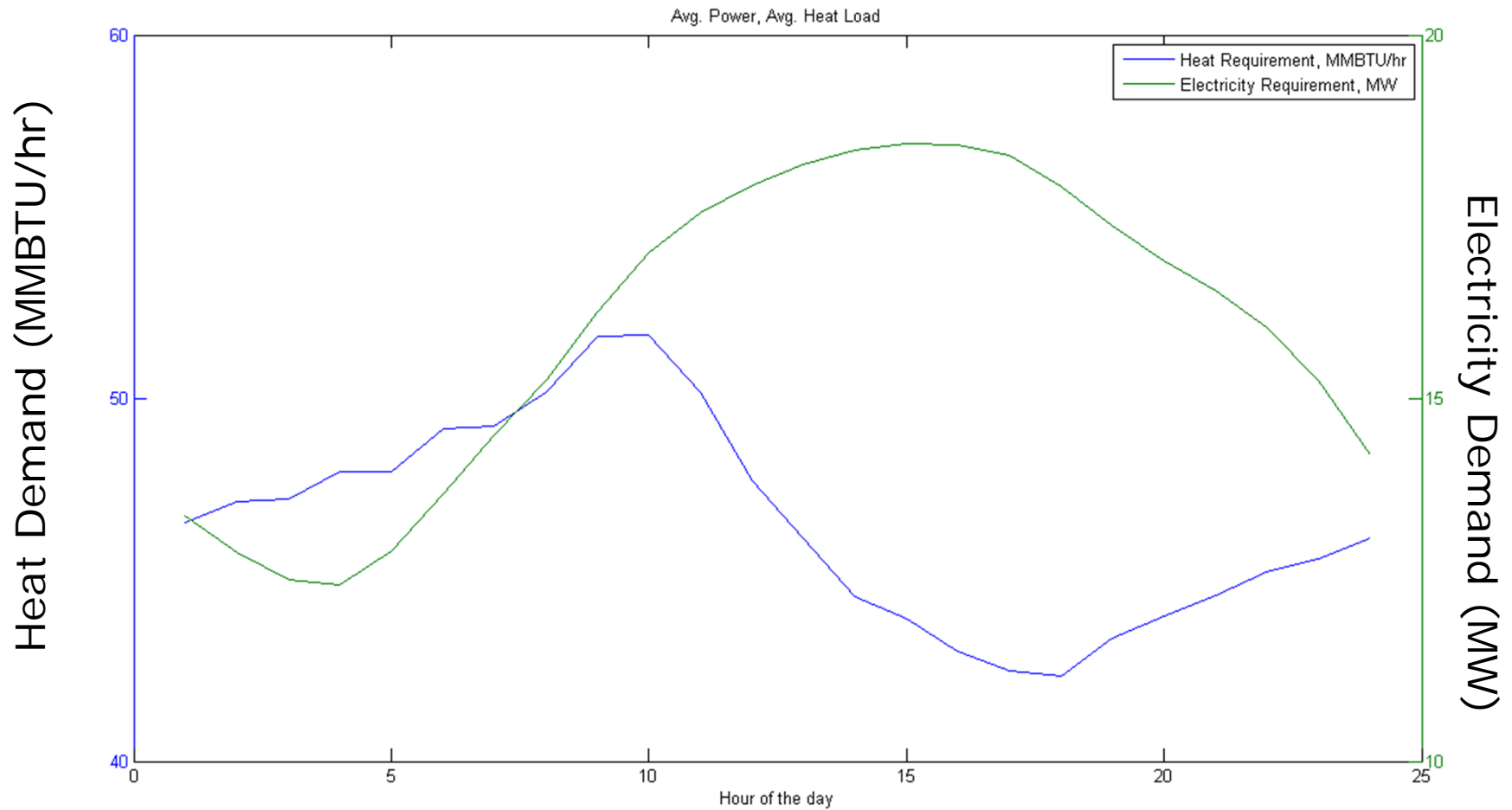
District Heating and Cooling



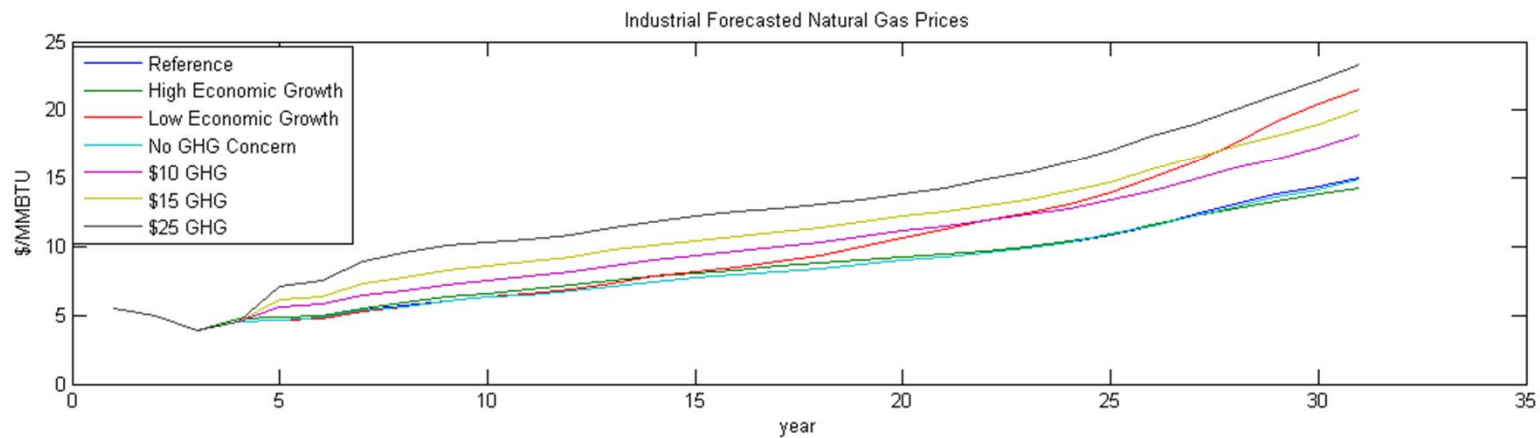
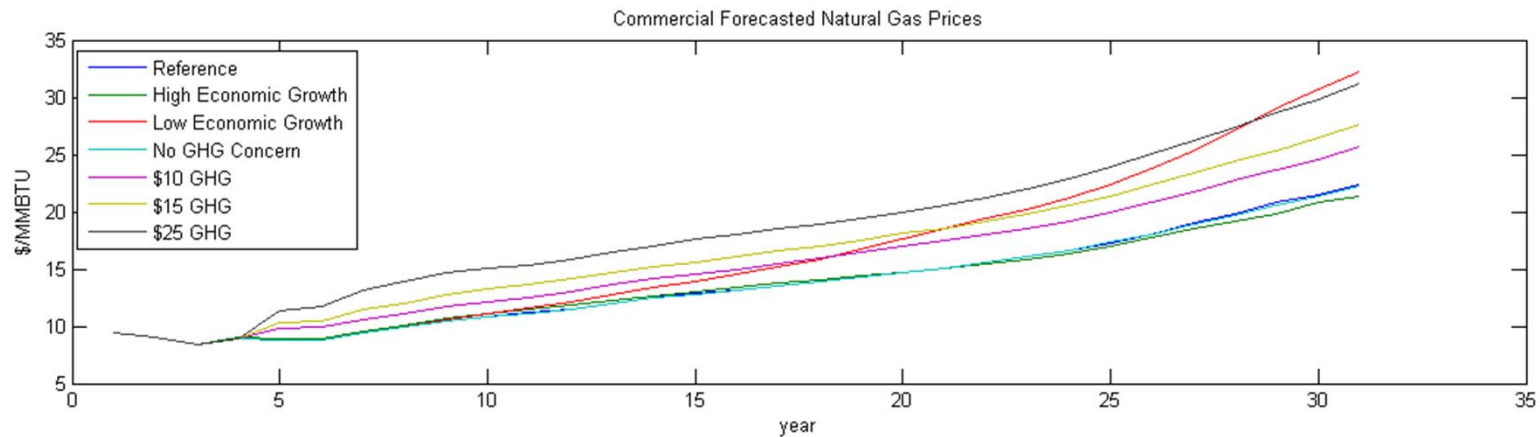
Planning of Investment Decisions



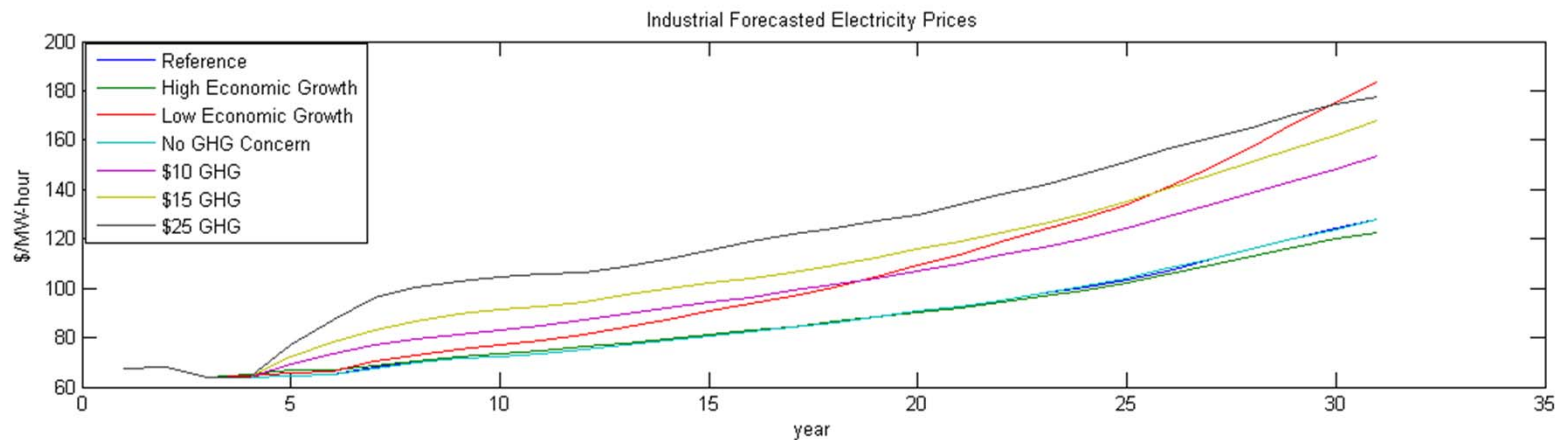
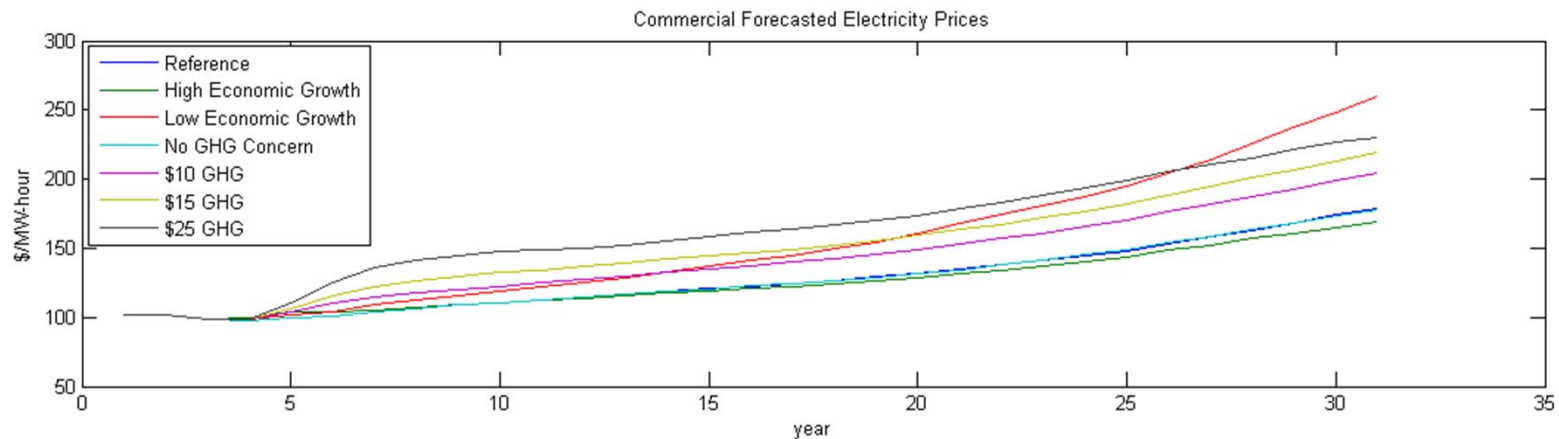
District Energy Profiles



Uncertainty in Natural Gas Prices

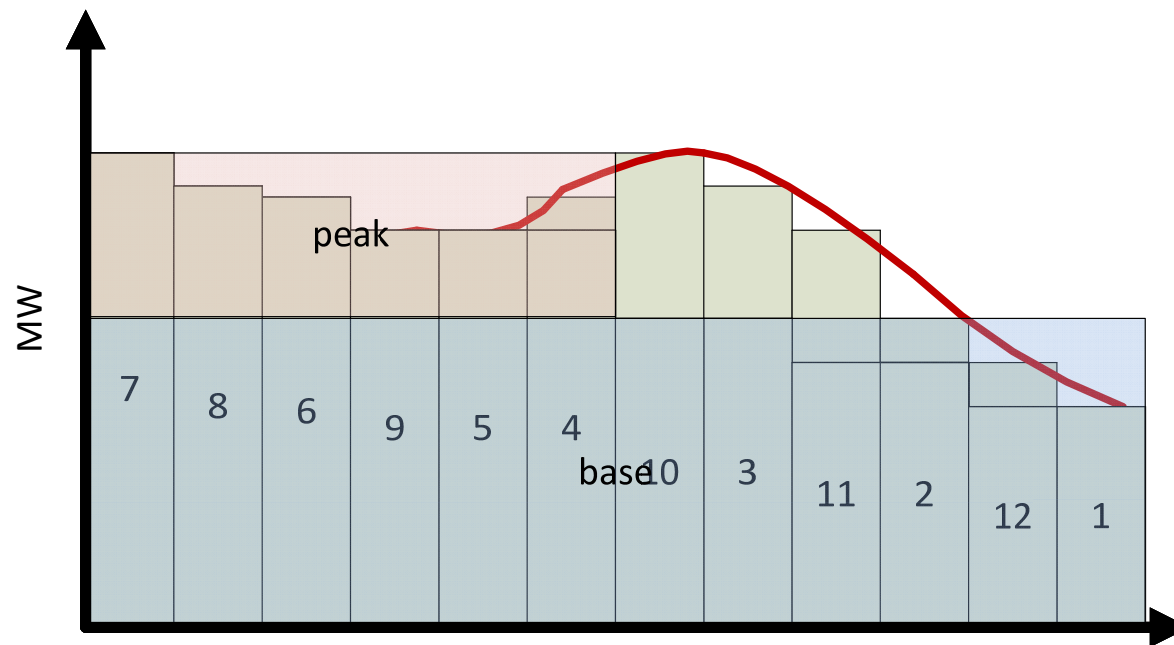


Uncertainty in Electricity Prices

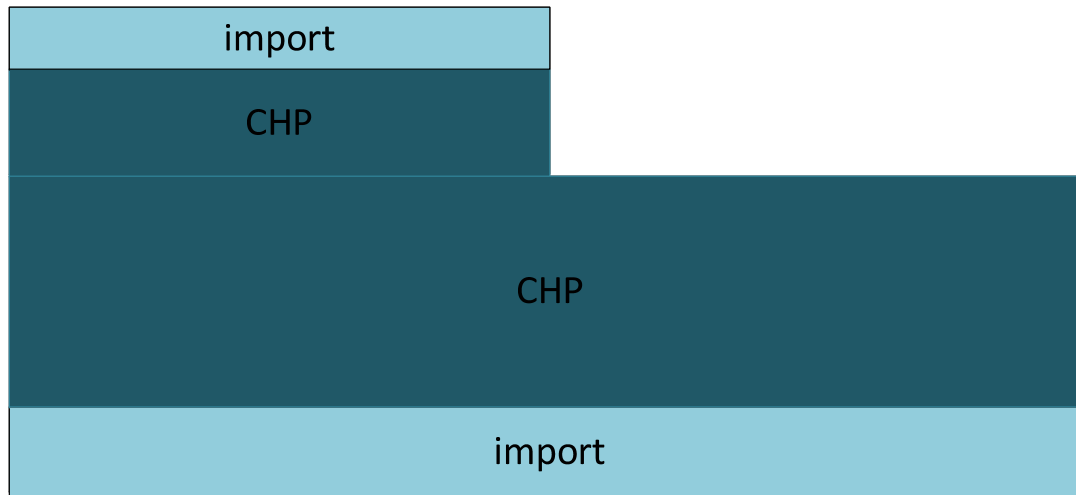


Simplifying System

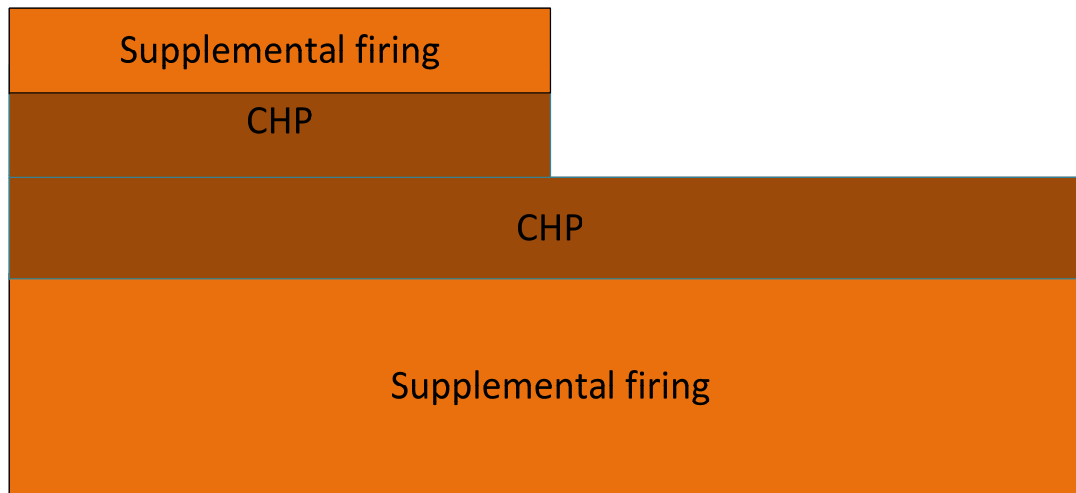
- Create Model:
- Electric and Heating Demand Model (winter and summer)



Allocation of energy supply

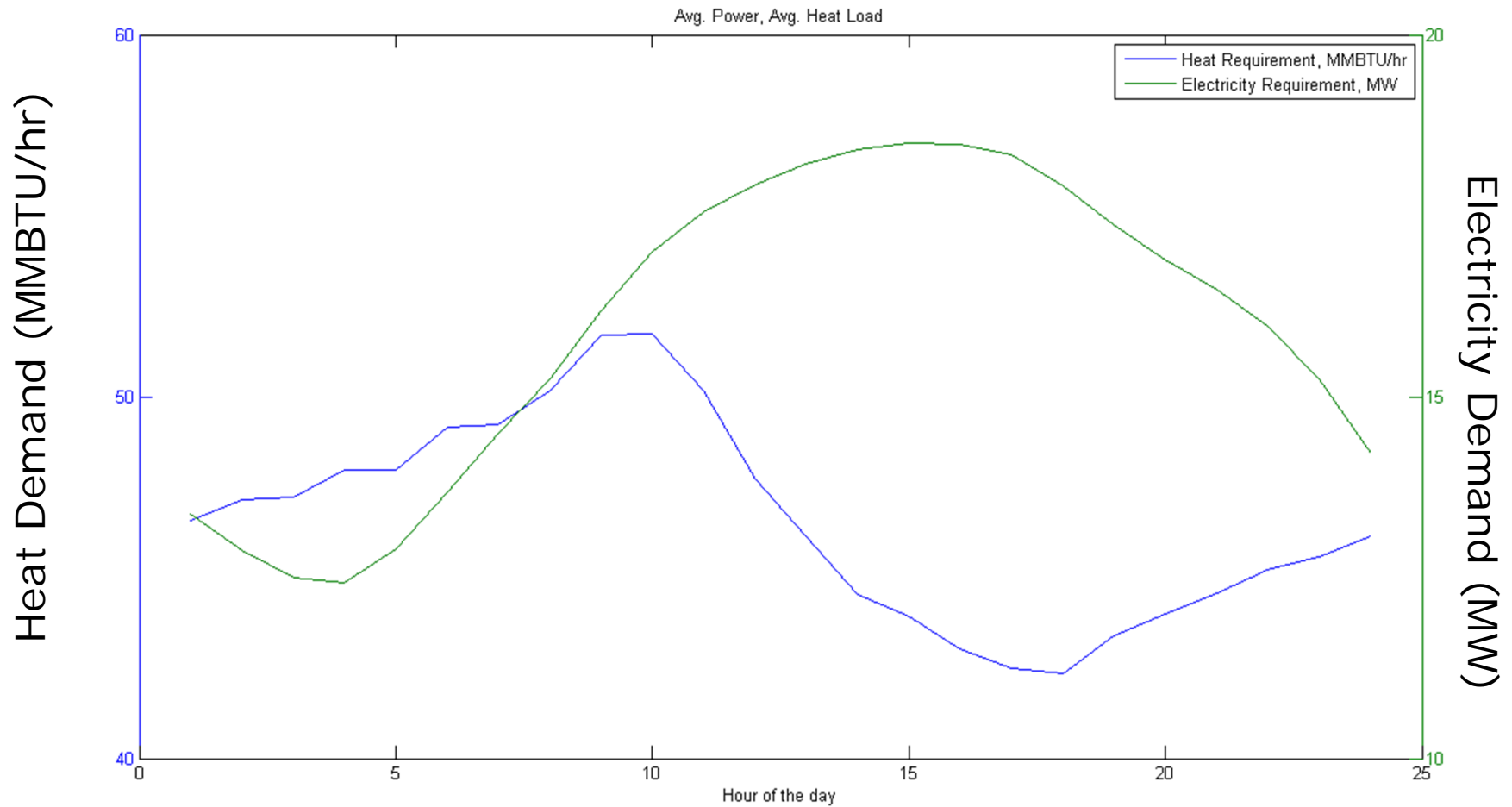


Summer Electricity
Supply Allocation?



Winter Heating
Capacity
Allocation?

Dynamic Model for Dynamic System



Nonlinear DAE

$$\min J(x, y, u) = (Cost_{capital} + Cost_{operating} + Cost_{environmental})$$

$$s.t. \quad 0 = f\left(\frac{\partial x}{\partial t}, x, y, u\right)$$

Nonlinear Cost functions

Turbine and boiler dynamics

$$0 = g(x, y, u)$$

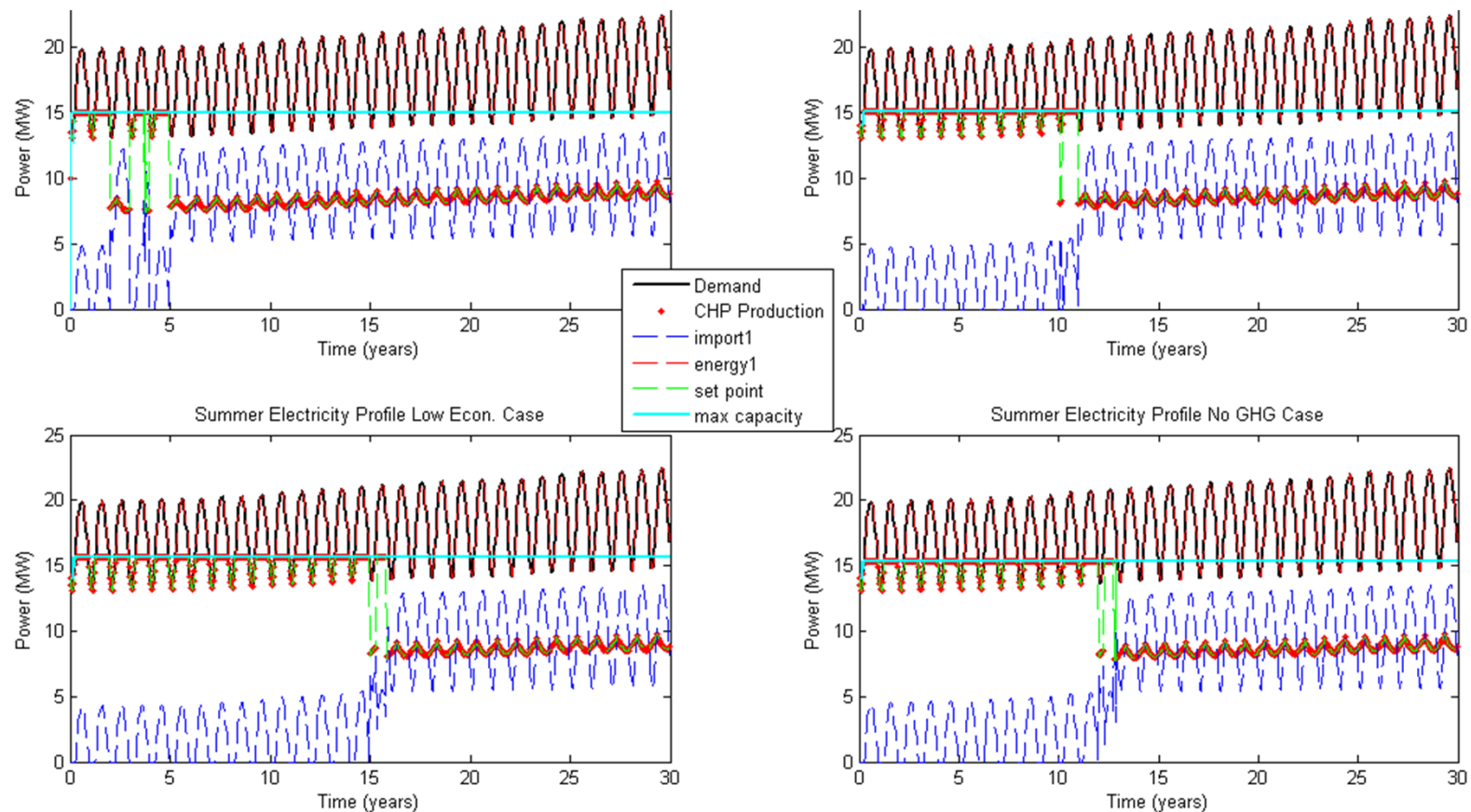
Demand and operating constraints

$$0 < h(x, y, u)$$

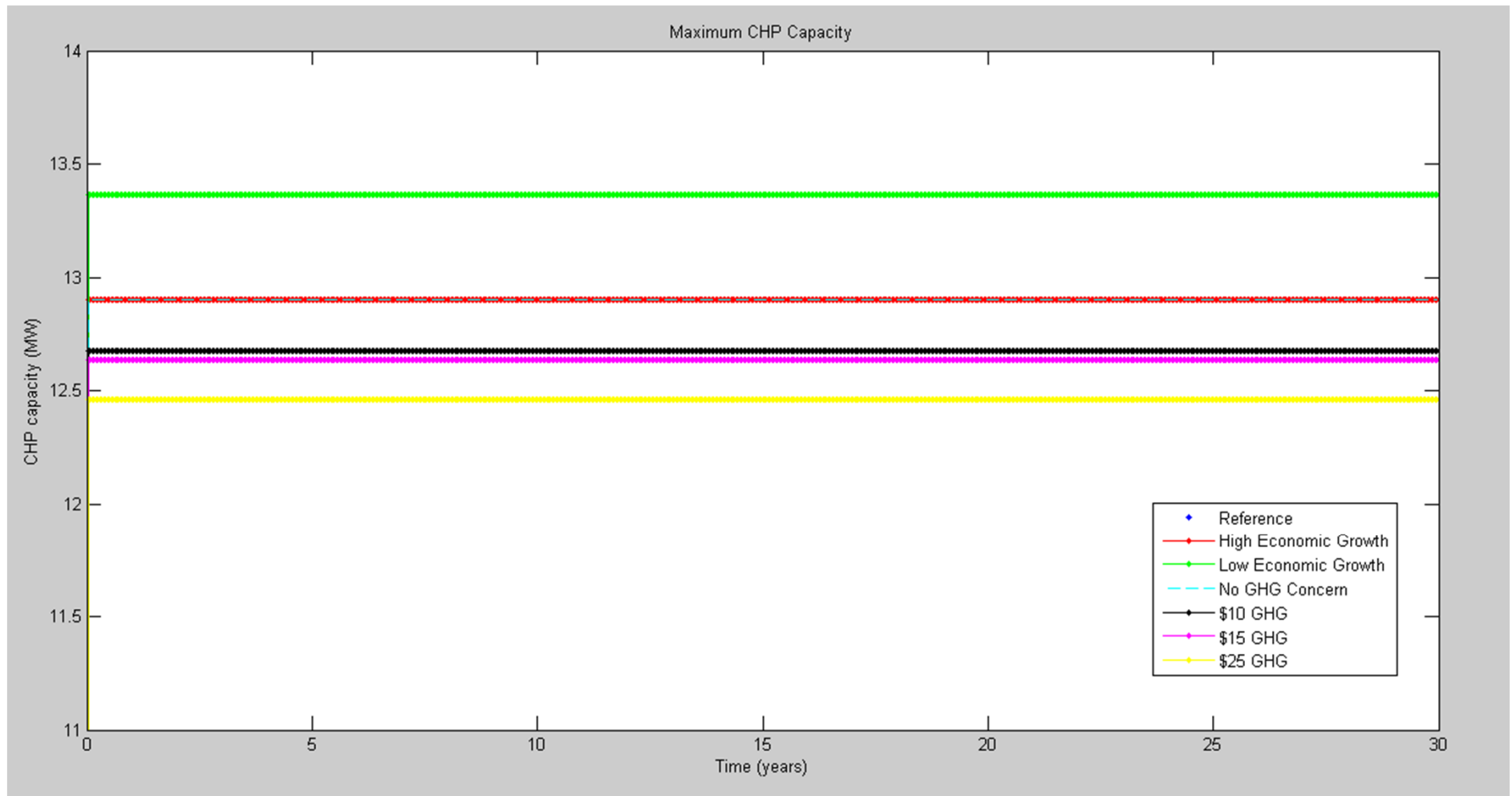
$$x, y \in \mathbb{R}^n \quad u \in \mathbb{R}^m$$

Dynamic Optimization Results

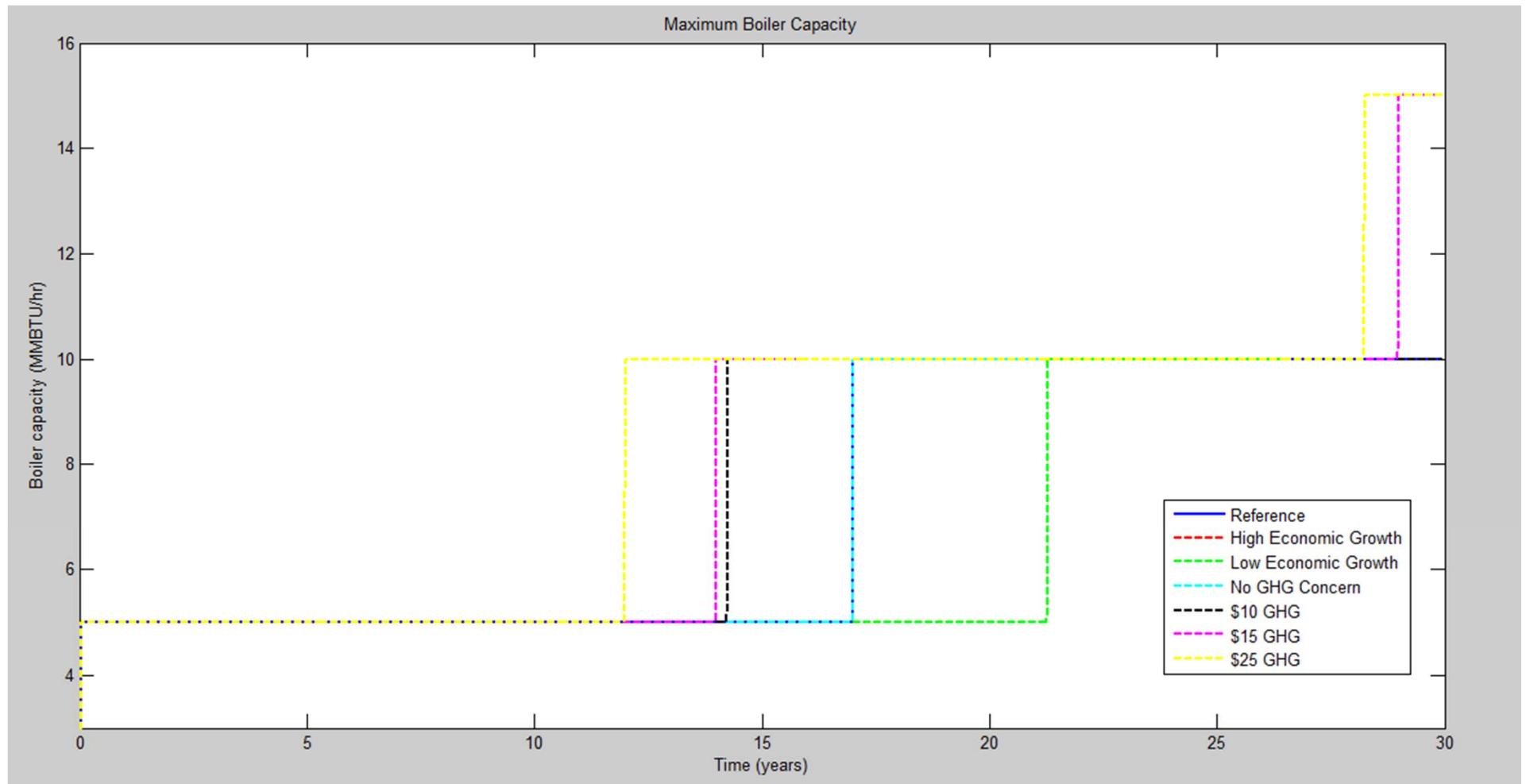
Both capacity increase and cost effective mode of operation over a long term horizon



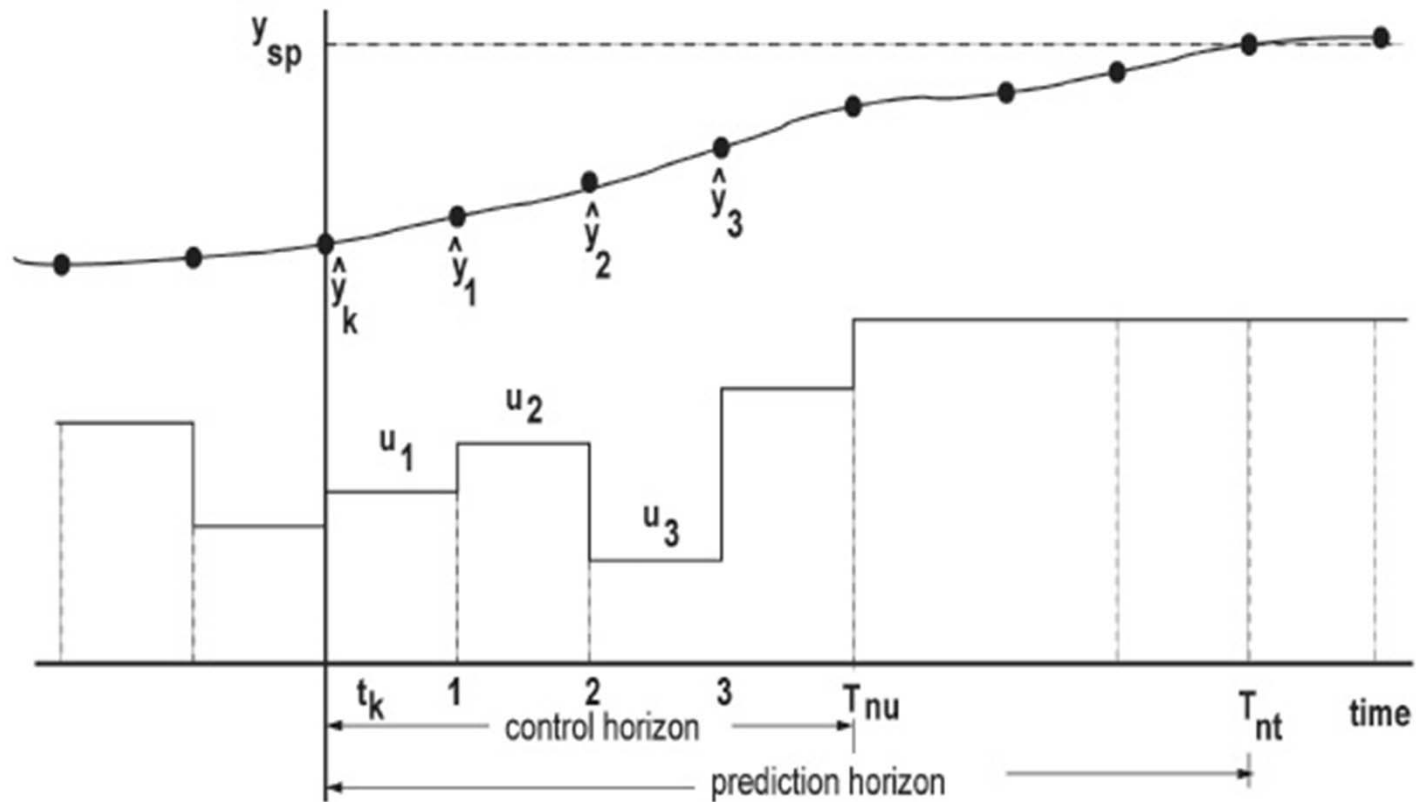
Turbine Max Capacity



Supplemental Boiler Firing Capacity



Model Predictive Control Approach



L1 Norm formulation

$$\min(obj + se_{hi} + se_{lo} + sc_{hi} + sc_{lo})$$

s.t.

$$0 = f(\dot{x}, x, d)$$

$$m_{gap} = \frac{m_{hi} - m}{2}$$

$$m_{gap} = \frac{m - m_{lo}}{2}$$

$$e_{hi} = x - m_{hi} + se_{hi}$$

$$e_{lo} = m_{lo} - x + se_{lo}$$

$$c_{hi} = x - \hat{x} + sc_{hi}$$

$$c_{lo} = \hat{x} - x + sc_{lo}$$

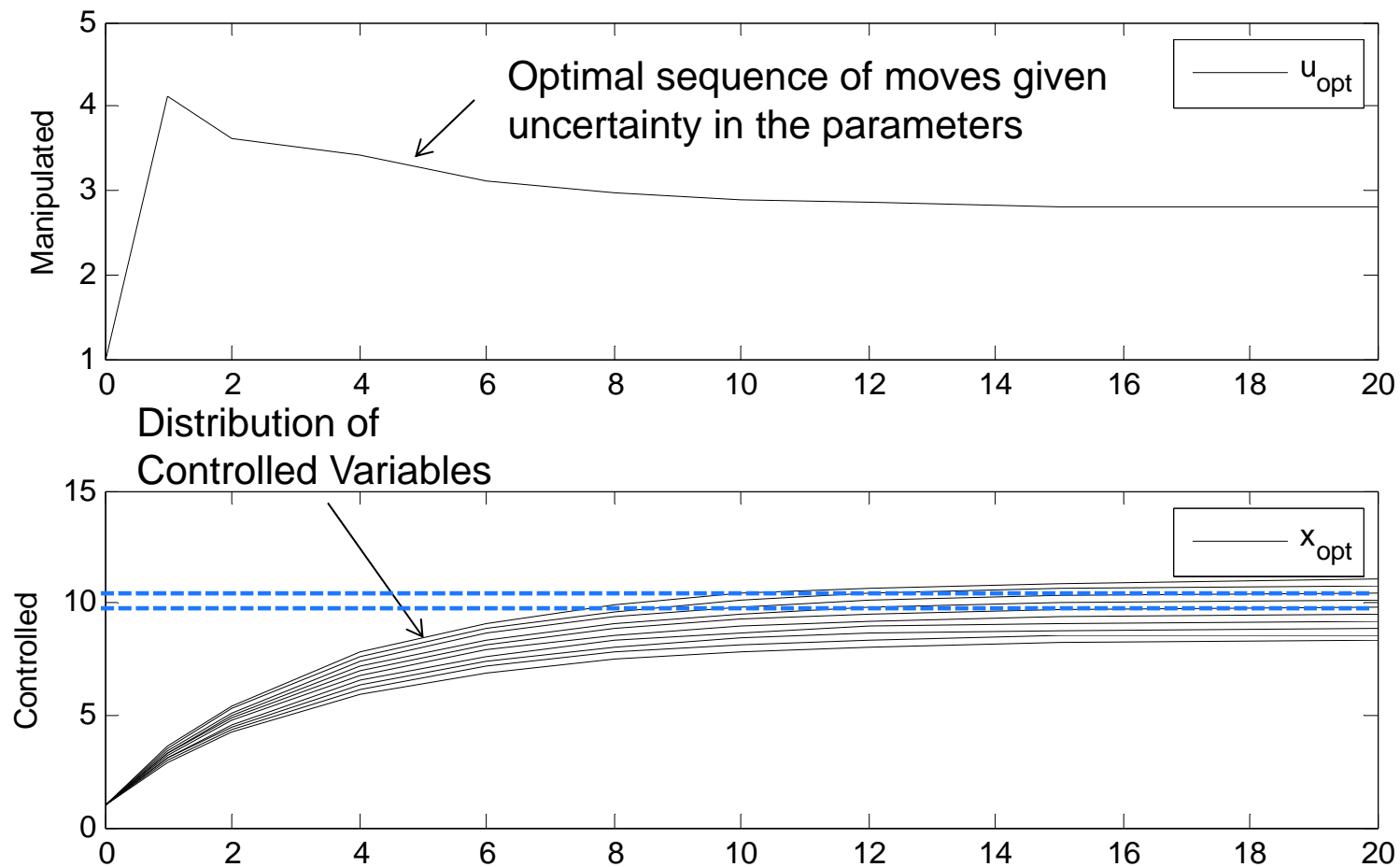
$$obj = w_{meas}(e_{hi} + e_{lo}) + w_{model}(c_{hi} + c_{lo}) + (Cost_{capital} + Cost_{operating} + Cost_{environmental})$$

$$se_{hi}, se_{lo}, sc_{hi}, sc_{lo} \geq 0$$

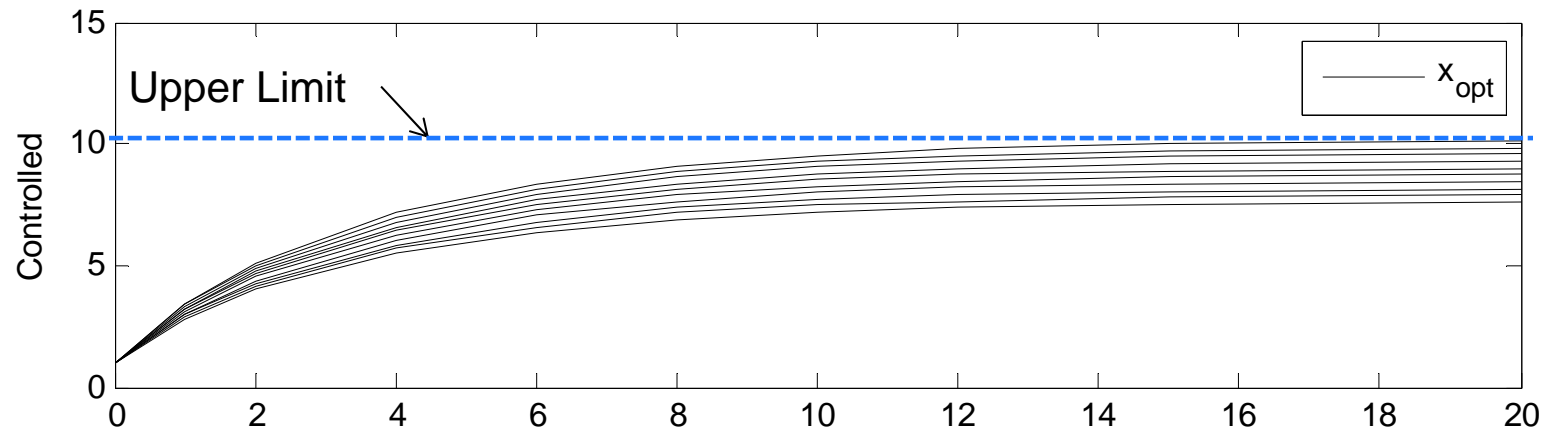
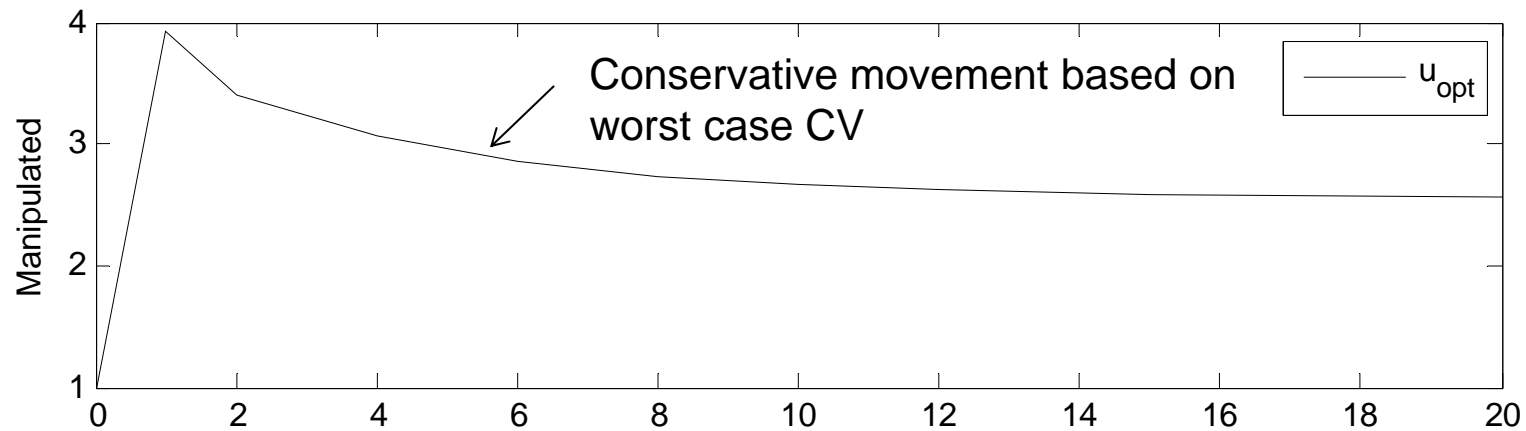
$$e_{hi}, e_{lo}, c_{hi}, c_{lo} \geq 0$$



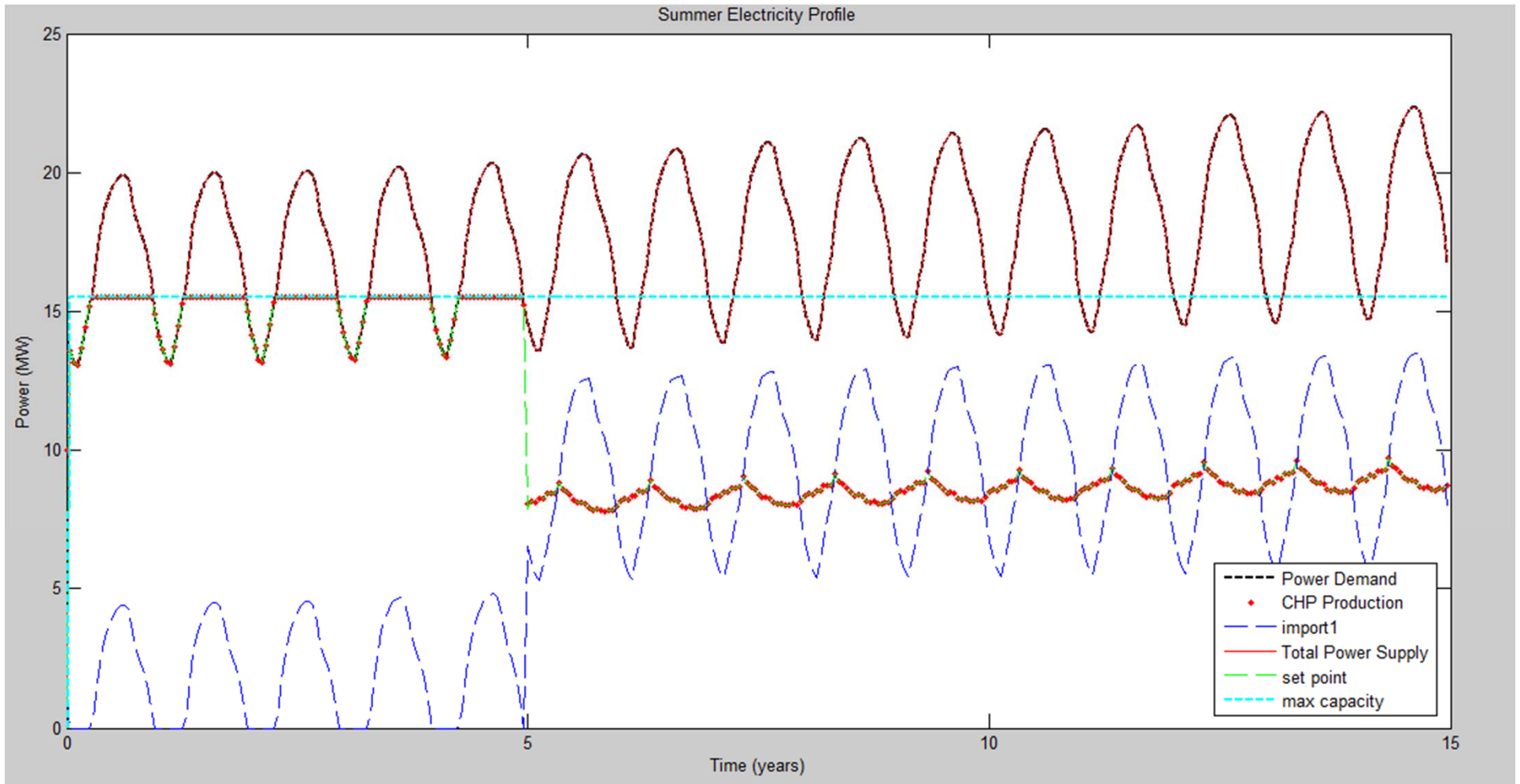
Optimize to a Target Range



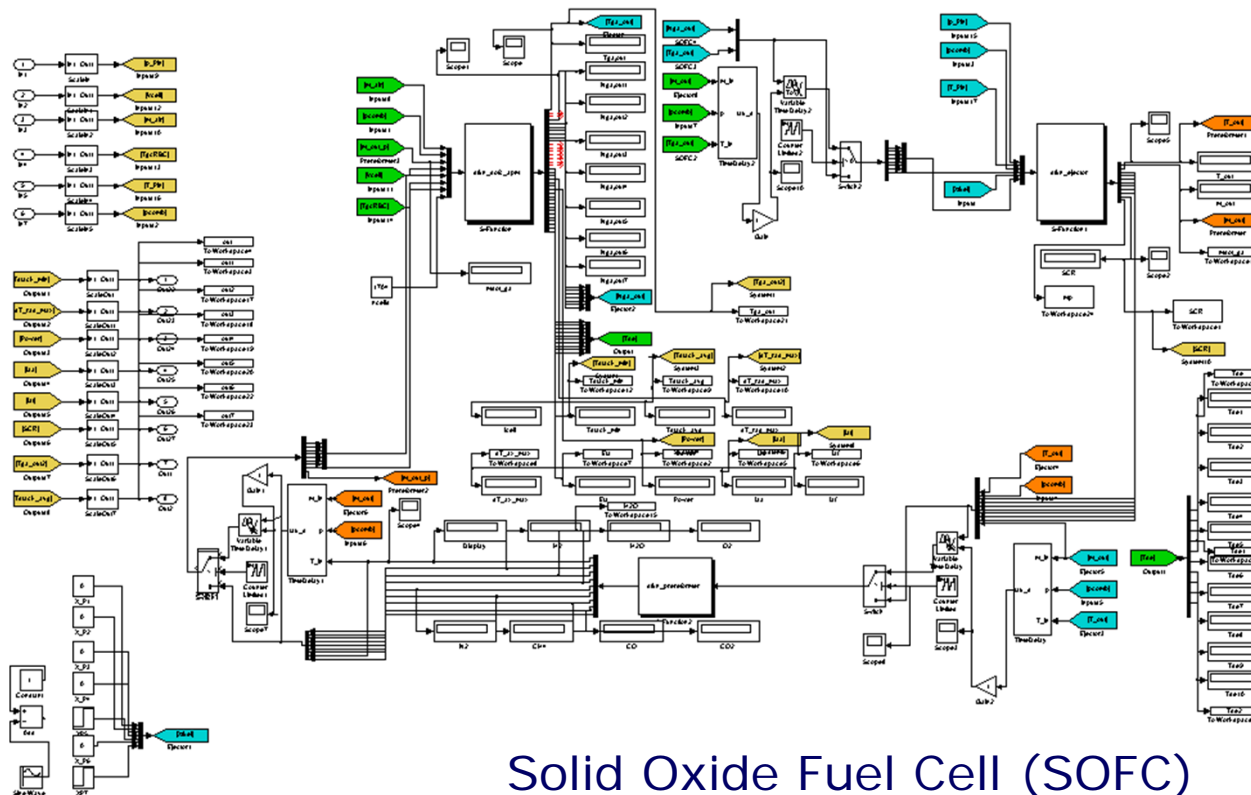
Optimize to a Limit



Dynamic Solution

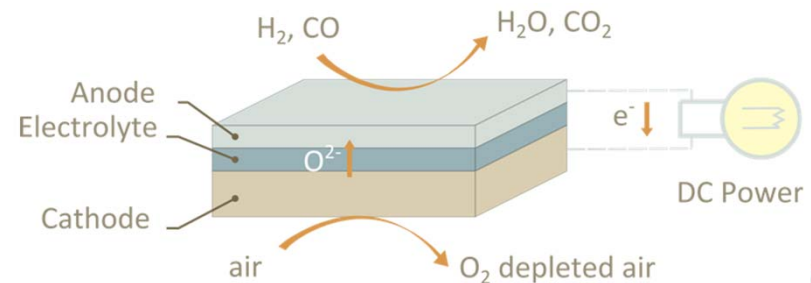
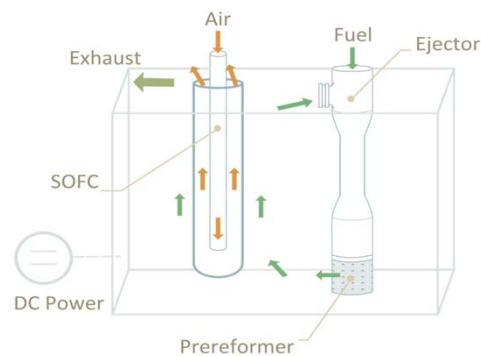


Dynamic Energy System Tools

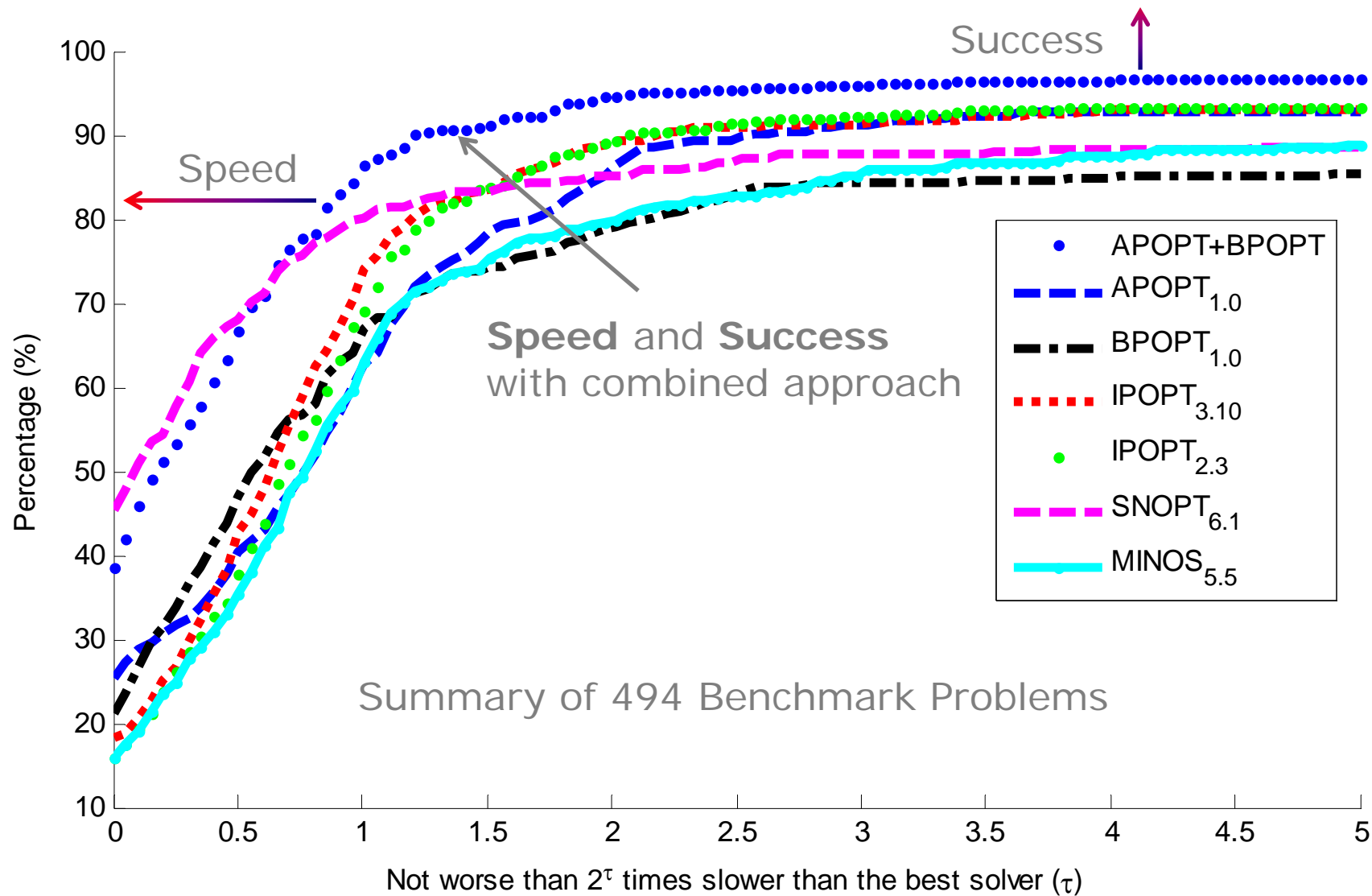


Toolbox for Object Oriented Modeling in MATLAB, Simulink, and Python

Advanced tools are required for collaborative modeling and high performance computing



Optimization Benchmark



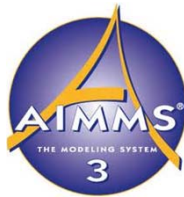
Conclusions

- Powerful insights can be gained from modeling and data reconciliation over long periods of historical data
- When data, modeling, and optimization are combined, hidden savings are discovered through dynamic optimization
- MPC approach can allow for other control variables to be accounted for directly in optimization
- Simulation and optimization of energy system can give stakeholders realistic options to evaluate risks and rewards with minimum cost
- Simulation results can then be directly applied to control applications

Development Needs

- Collaborative modeling tools
- Library of high quality models that are open source and can be adapted to new problems
- Improvements to methods to simulate and optimize large-scale and complex systems
- Interface with operations and subject matter experts – need to know the process for effective modeling and optimizing

Acknowledgements

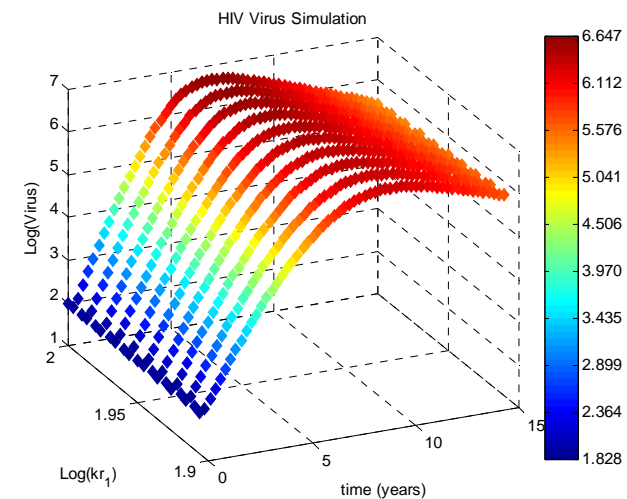
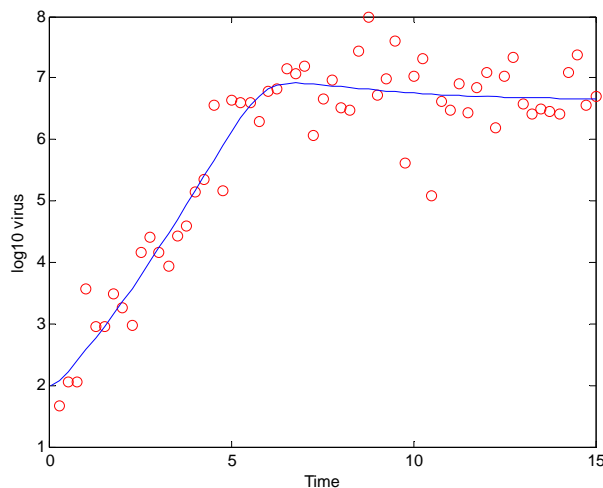


Extra Slides



Systems Biology

- Objective: Improve extraction of information from clinical trial data
- Dynamic data reconciliation
 - Dynamic pharmacokinetic models (large-scale)
 - Data sets over many patients (distributed)
 - Uncertain parameters (stochastic)



Energy System Model

Parameters :

e_p = existing capacity of plant type p [MW]
 cc_p = daily fraction of capital cost of plant p [MW]
 oc_p = daily operating cost of plant p [USD/MWh]
 $ic_{k,s}$ = electricity import cost [USD/MWh]
 $d_{k,s,i}$ = instantaneous energy demand [MW]
 $du_{k,s,i}$ = duration of demand [h]
 $r_{k,s,i}$ = required energy [MWh]
 f_{hrq} = recovered heat factor [unitless]

where the parameter r_k is defined as $r_{k,s,i} = (d_{k,s,i} - d_{k-1,s,i}) \cdot du_{k,s,i}$

Indices :

p plant type {chp, boiler}
 k demand category {base load, peak load}
 s season {summer, winter}
 i energy type {electric, thermal}

Variables :

x_p = new design of plant type p [MW]
 $y_{p,k,s}$ = allocation of capacity to demand [MW]
 $z_{k,s}$ = import of electricity [MW/h]

LP (Linear Programming)

Minimize :

$$\sum_p cc_p(e_p + x_p) + \sum_k \sum_s ic_{k,s} \cdot z_{k,s} + \sum_k \sum_s \sum_i du_{k,s,i} \left(\sum_p oc_p \cdot y_{p,k,s} \right)$$

Subject to :

$$e_p + x_p \geq \sum_k \sum_s y_{p,k,s} \quad \text{for all } p$$

$$r_{k,s,electric} = z_{k,s} + du_{k,s,electric} \left(\sum_p y_{chp,k,s} \right) \quad \text{for all } k, s$$

$$r_{k,s,thermal} \leq du_{k,s,electric} \left(\sum_p y_{boiler,k,s} + y_{chp,k,s} \cdot f_{hrg} \right) \quad \text{for all } k, s$$

$$x_p \geq 0$$

$$y_{p,k,s} \geq 0$$

$$z_{k,s} \geq 0$$

Example of Results

		CapacityAllocationPlan [MW]																																
		c1				c2				c3				c4				summer				c5				c6				c7				F
		Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV					
boiler	base																																	
	peak																																	
chp	base	15.0	15.0	15.0	18.0	15.0	15.1	15.8	18.0	15.0	15.3	16.5	18.0	15.0	15.5	17.4	18.0	15.0	15.6	18.2	18.0	15.0	15.8	19.1	18.0	15.0	15.9	20.0	18.0					
	peak	2.0	2.6	2.6	2.0	2.0	2.7	2.8	2.0	2.0	2.7	2.9	2.0	2.0	2.5	2.6	2.0	2.0	2.4	1.8	2.0	2.0	2.3	0.9	2.0	2.0	2.1		2.0					

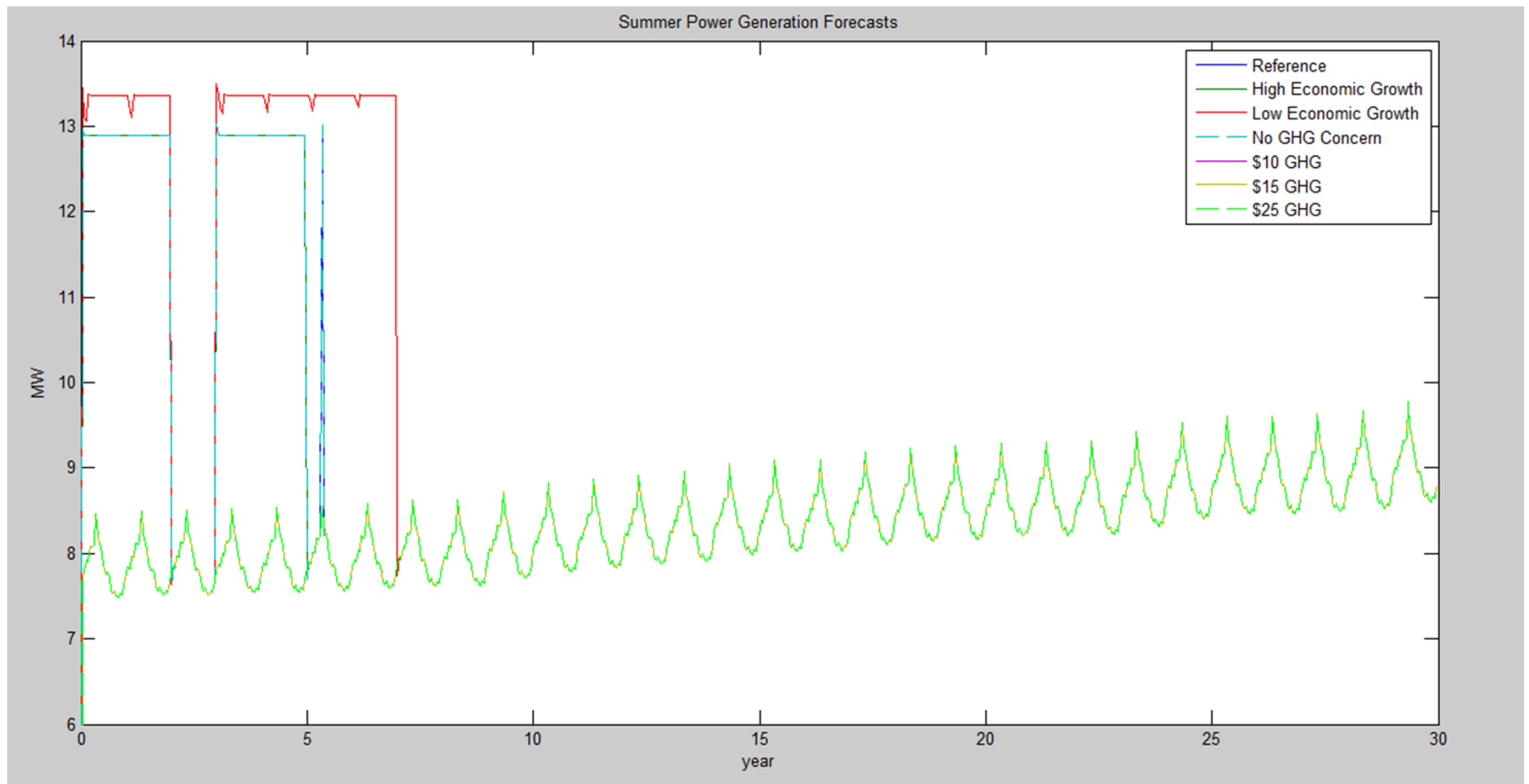
		CapImportedPlanMW [MW]																											
		c1				c2				c3				c4				c5				c6				c7			
		Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV	Plan I	Plan II	Plan III	Plan IV
base	summer																									0.10			
summer	winter																												
peak	summer	3.00	2.35	2.35	4.00	3.00	2.38	2.47	4.00	3.00	2.40	2.59	4.00	3.00	2.60	3.15	4.00	3.00	2.80	4.31	4.00	3.00	3.00	5.53	4.00	3.00	3.20	6.70	4.00
winter		1.53	1.53	1.53	1.53	1.53	1.54	1.61	1.53	1.53	1.56	1.69	1.53	1.53	1.58	1.77	1.53	1.53	1.60	1.88	1.53	1.53	1.62	2.97	1.53	1.53	1.62	4.12	1.53

		NewCapPlan [MW]			
		Plan I	Plan II	Plan III	Plan IV
boiler	c1				
	c2				
	c3				
	c4				
	c5				
	c6				
	c7				
	c8				
chp	c1	17.0	18.0	20.0	20.0
	c2				
	c3				
	c4				
	c5				
	c6				
	c7				
	c8				

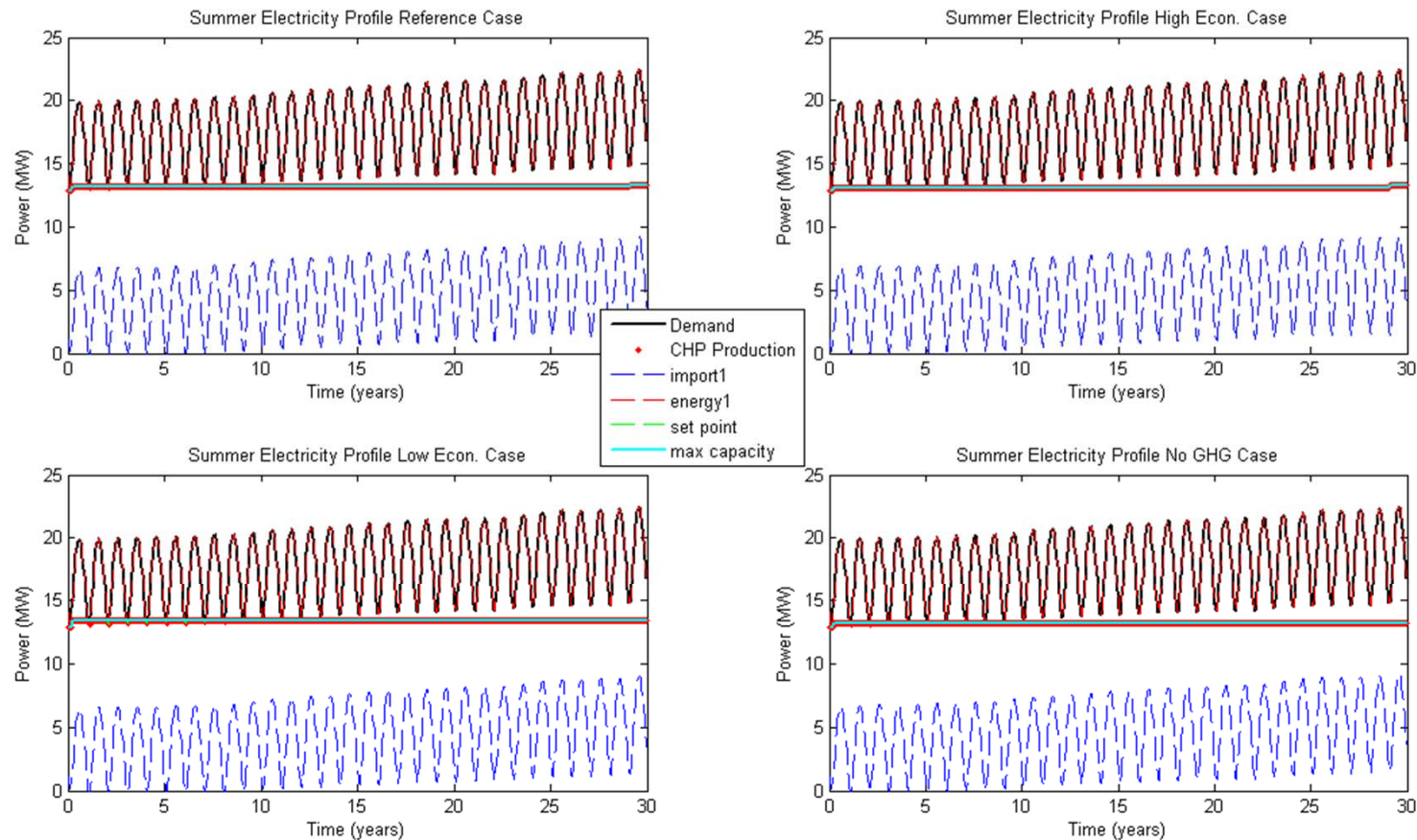
LP or NLP formulation, optimizing through discrete scenarios to account for uncertainty. Lacks system dynamics.



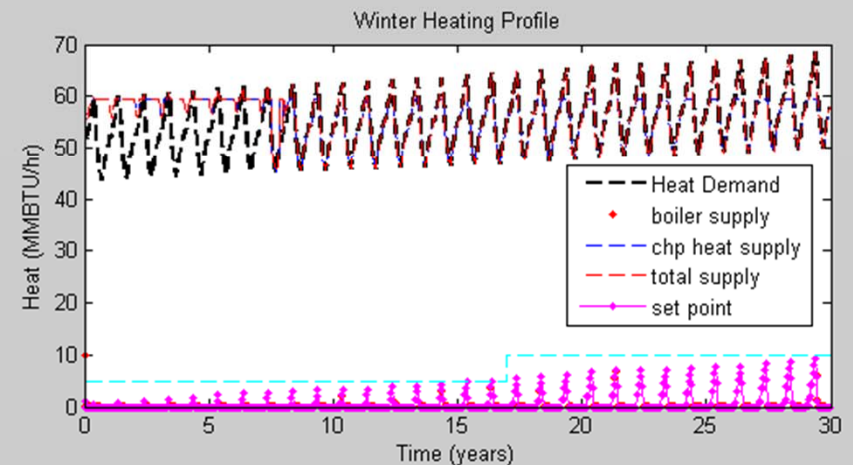
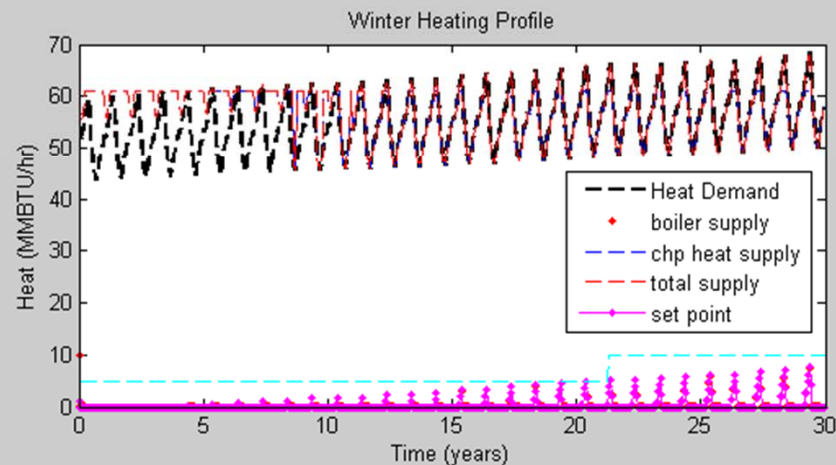
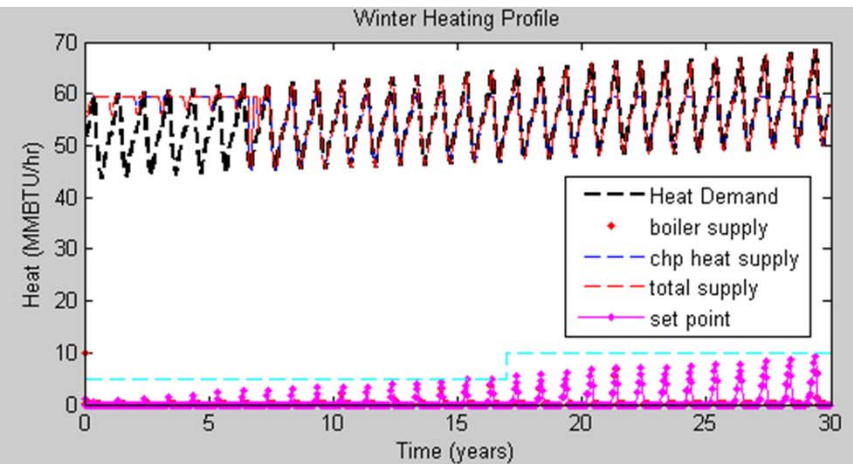
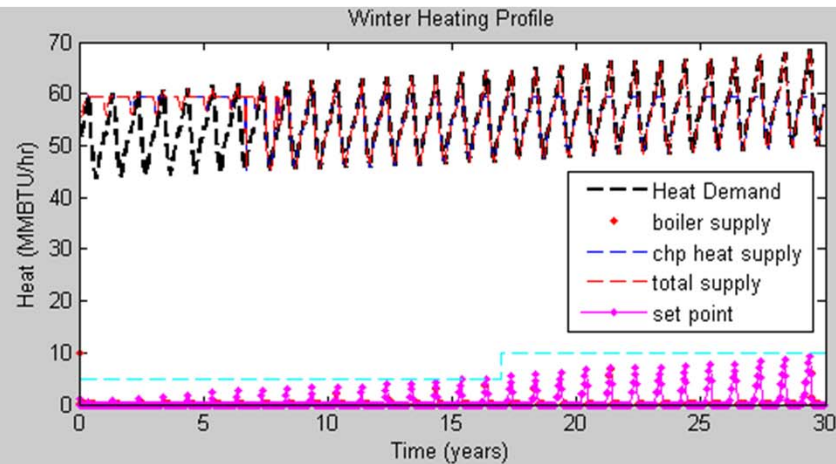
Electricity Generation Forecasts



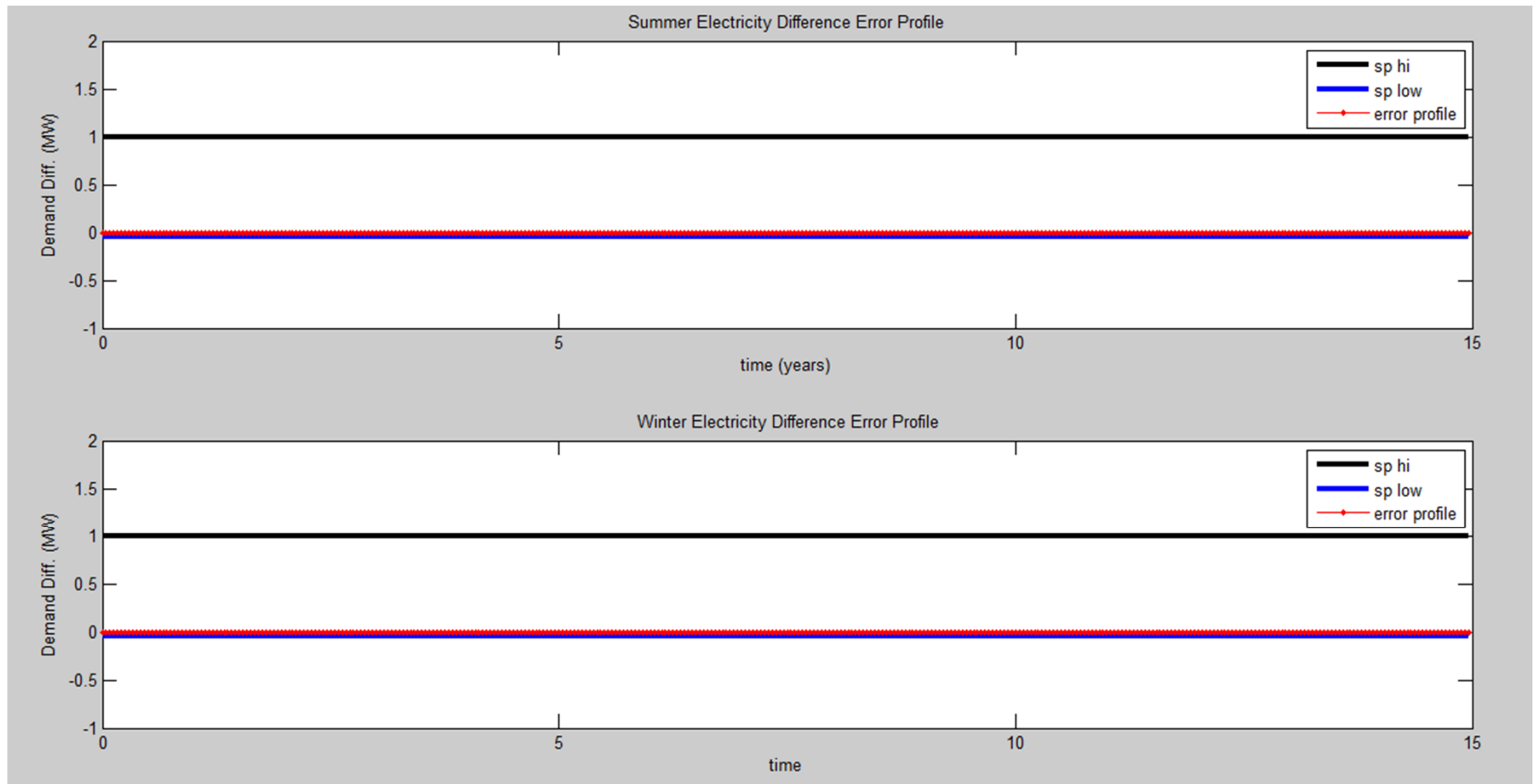
Optimize capacity at CHP's most efficient operating point



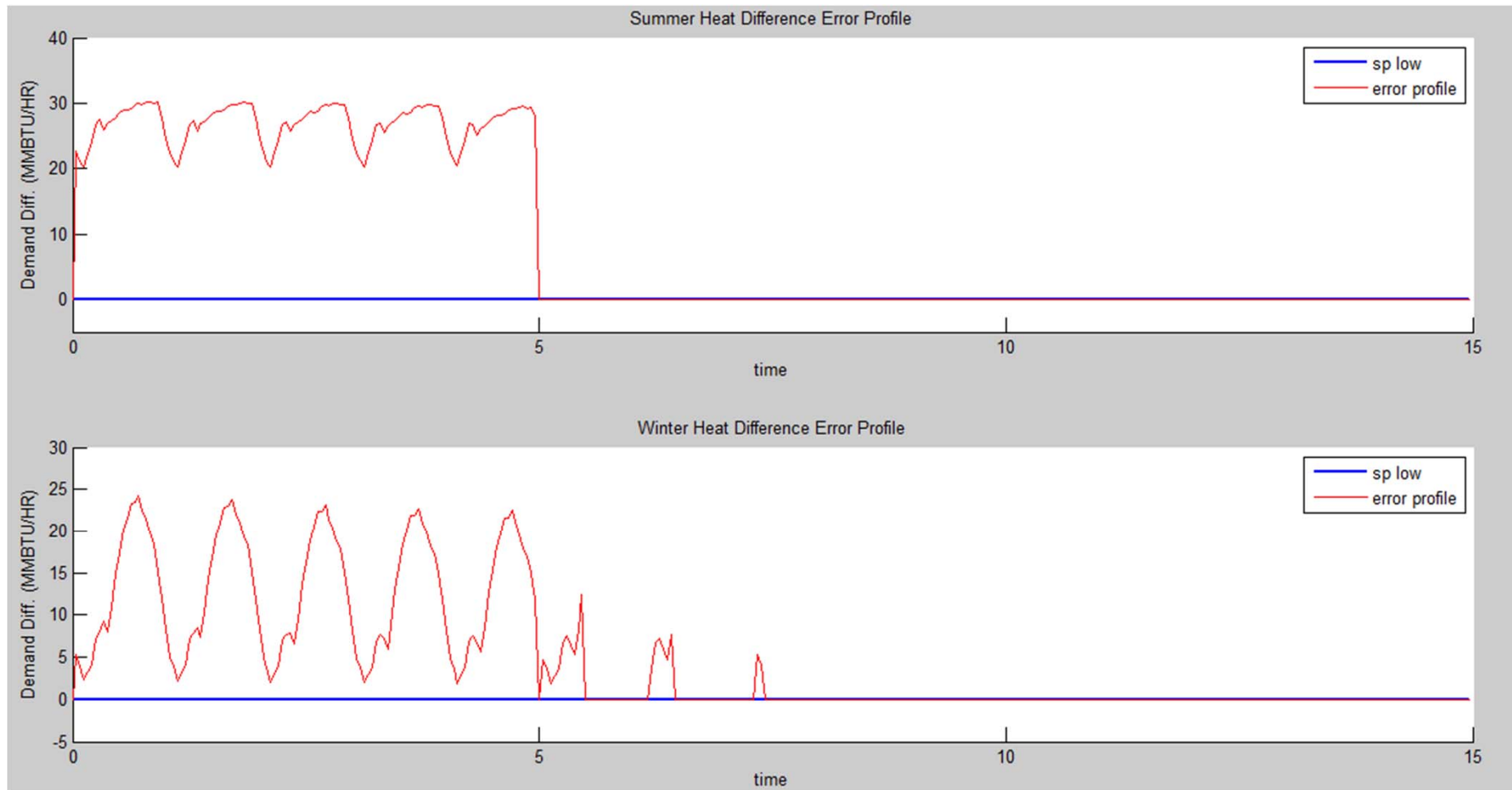
Heat load is optimized simultaneously



Optimize to a Target



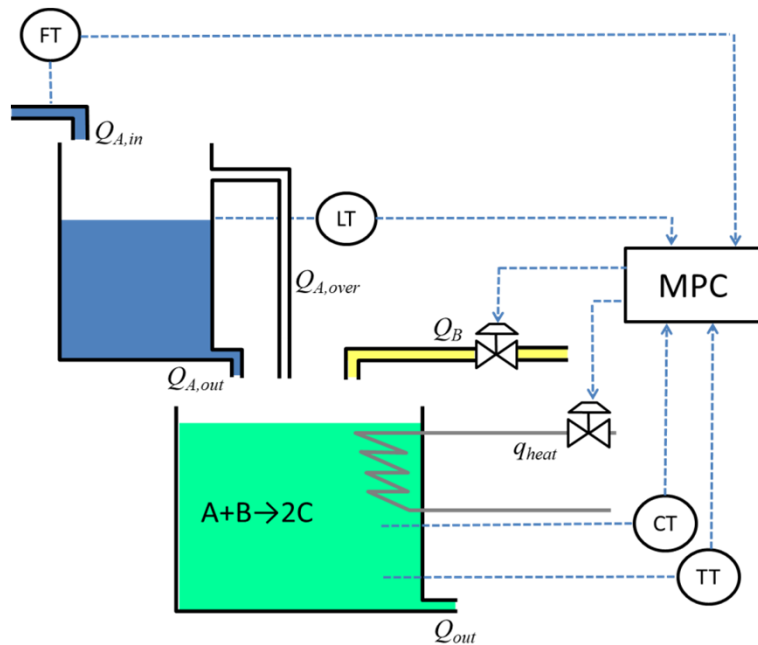
Optimize above a Limit



Simultaneous vs. Sequential

Table 1: Computational results from the sequential and simultaneous solution methods. Computations for each method are executed using an Intel ® Core 2 Duo ™ (2.54 GHz) processor with 4 GB RAM.

	Sequential	Simultaneous
Objective function value	0.0094	0.0108
System model evaluations	3,336	1
Computation time (s)	331.6	1.1



K.M. Powell, J.D. Hedengren, T.F. Edgar, A Continuous Formulation for Logical Decisions in Differential Algebraic Systems using Mathematical Programs of Equilibrium Constraints, Industrial and Engineering Chemistry Research, Submitted, 2013.



Survey of DAE Solvers

<u>Software Package</u>	<u>Max DAE Index</u>	<u>Form</u>	<u>Adaptive Time Step</u>	<u>Sparse</u>	<u>Partial-DAEs</u>	<u>Simultaneous Estimation / Optimization</u>
APMonitor	3+	Open	No	Yes	No	Yes
DASPK / CVODE / Jacobian	2	Open	Yes	No	No	No
gProms	1 (3+ with transforms)	Open	Yes	Yes	Yes	No
MATLAB	1	Semi-explicit	Yes	No	No	No
Modelica	1	Open	Yes	Yes	No	No

DAE = Differential and Algebraic Equation

