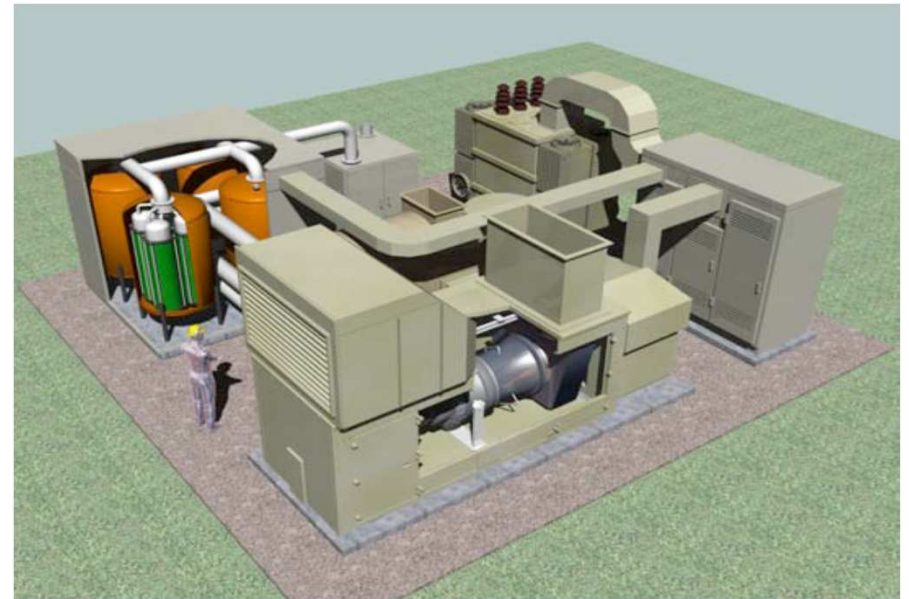


# Dynamic Modeling of Reliability Constraints in Solid Oxide Fuel Cells and Implications for Advanced Control

AICHE Fall 2010 Annual Meeting

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\*GE, 2007

# Overview

## Modeling and Controls Objective:

Maintain solid oxide fuel cell (SOFC) performance and operational integrity subject to load-following, efficiency maximization, and disturbances using advanced process control.

## Agenda:

- Motivation and Overview of Tubular SOFC System
- Distributed-Parameter SOFC Modeling
- SS and Dynamic Simulations of Fuel Cell Operation
- Conclusion

# Research Motivation

## Benefits

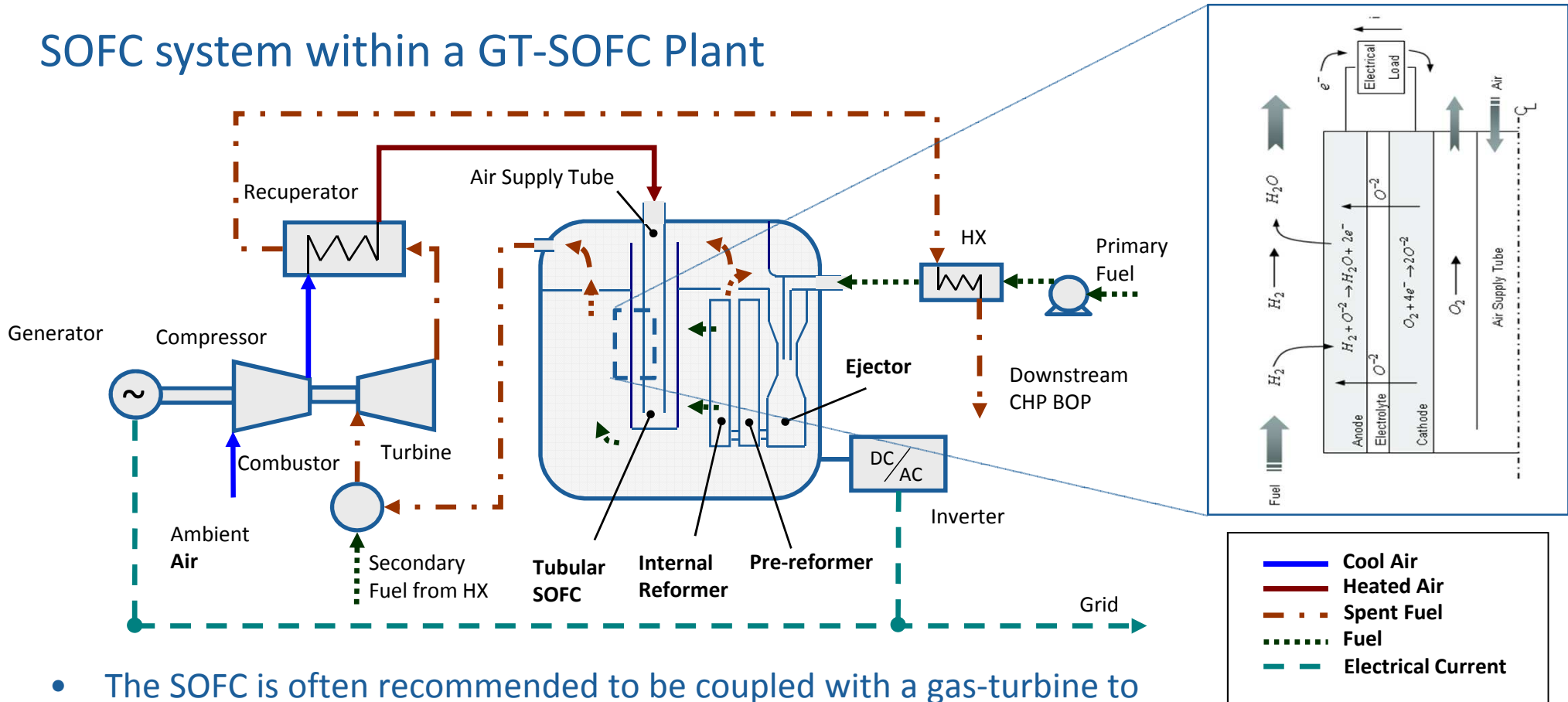
- High efficiencies at full and partial load:  
40-50% (LHV) for SOFC for 200 kW, 60-70% for GT-SOFC, 90%+ for cogeneration.
- Fuel flexibility:
  - Hydrogen, natural gas, propane
  - Alcohols, biomass, coal gas
- Suitability for cogeneration with high exhaust temperatures
- Low noise and emission levels

## Operational Challenges

- Micro-cracking, catalyst poisoning, and air & fuel starvation decrease the lifetime and increase cost of electricity.
- Majority of real plants have used SISO PID and PLC control – operations experience with advanced control is limited.

# SOFC System Overview

## SOFC system within a GT-SOFC Plant

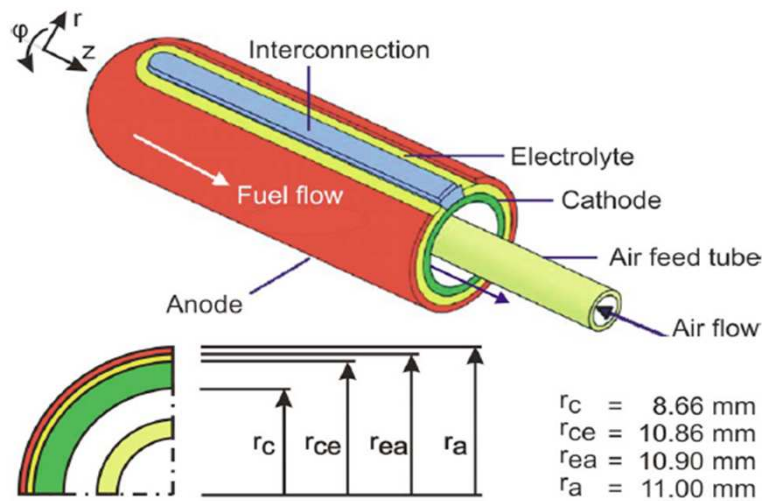


- The SOFC is often recommended to be coupled with a gas-turbine to utilize waste heat, maximize efficiencies, and supplement power production.
- Model of manipulated variables assumes an external variable speed compressor and recuperators.

# Distributed-Parameter SOFC Modeling

# Tubular SOFC Modeling

## Tubular Solid Oxide Fuel Cell Assembly



\*Image from Singhal, S.C., 2006.

**Type:** high-temperature tubular SOFC

**Structure:** cathode-supported

**Fuel:** prereformation and direct internal reformation of methane

**Balance of Plant in Model:** ejector and prereformer

Pressurized to 3 bar

Based on a Siemens-Westinghouse plant at National Fuel Cell Research Center.

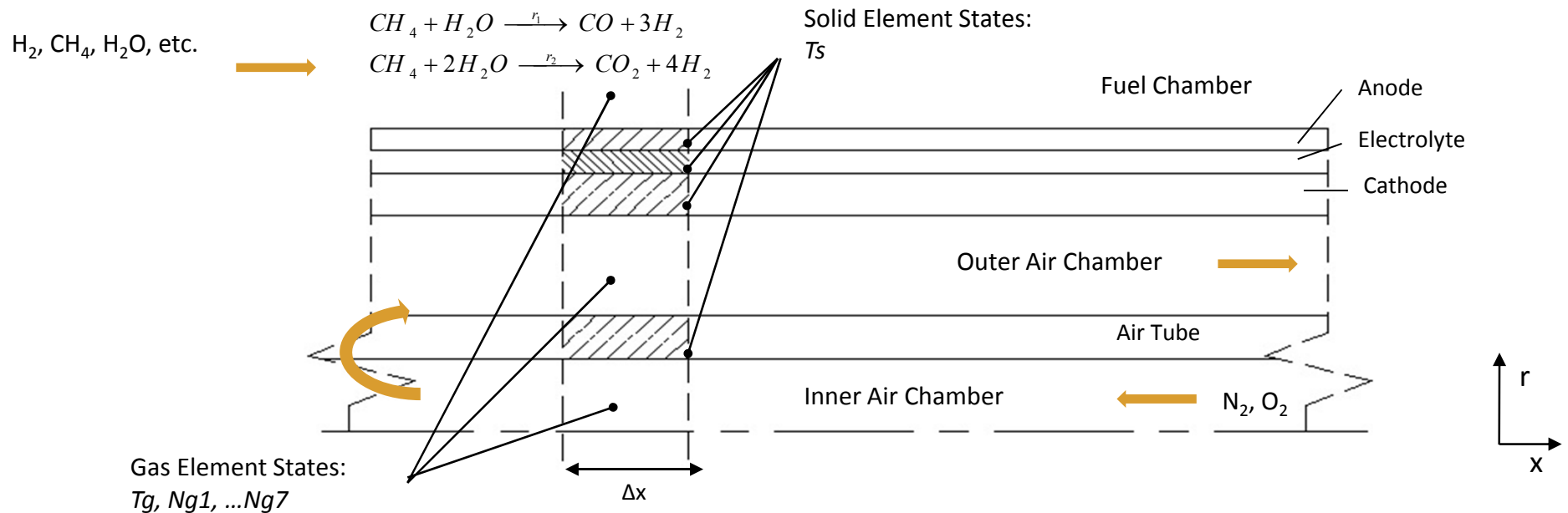
Parameters and inlet conditions are well known in literature versus other SOFC designs

# Dynamic Modeling Challenges

- Distributed parameter approach produces a large number of states: 220 states for 10 finite volumes in the axial direction.
- Dynamic system of differential and algebraic equations to be solved simultaneously (without algebraic loops).
- Algebraic equations are in an implicit form.
- Nonlinearities introduced by reaction and electrochemical terms.
- Multiple time scales varying from milliseconds to hours.

# Quasi-2D SOFC Model Discretization

## SOFC Cross-Section in Radial (r) and Axial (x) Directions



- Total States per Element = 22 : T<sub>ga</sub>, T<sub>sa</sub>, T<sub>se</sub>, T<sub>sc</sub>, T<sub>gc2</sub>, T<sub>sat</sub>, T<sub>gc1</sub>, Ng<sub>a1</sub>-Ng<sub>a7</sub>, Ng<sub>c21</sub>-Ng<sub>c27</sub>, I (current)
- Total States per SS Model = 878
- Total States per Dynamic Model = 220



# Key SOFC Model Equations

## Electrochemical Model

$$V_{cell} = E - \eta_a - \eta_c - \eta_r$$

$$E = E_0 + \frac{RT_{avg}}{2F} \ln \left( \frac{p_{H_2} p_{O_2}^{1/2}}{p_{H_2O}} \right)$$

$$E_0 = - \frac{\Delta G^r}{2F}$$

$$\eta_a = \frac{RT_{a,j}}{\alpha 2F} \ln \left( \frac{i}{i_0} \right) + \frac{RT_{c,j}}{\alpha 4F} \ln \left( \frac{i}{i_0} \right)$$

$$\eta_c = \frac{RT_{a,j}}{2F} \ln \left( 1 - \frac{i}{i_{l,a}} \right) + \frac{RT_{c,j}}{4F} \ln \left( 1 - \frac{i}{i_{l,c}} \right)$$

$$\eta_r = iR_{eff}$$

## Species and Energy Balances

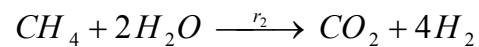
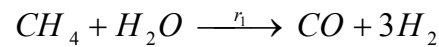
$$\dot{n}_{out} = \dot{n}_{in} + \sum_i \sum_j v_i r_{ij}$$

$$0 = \dot{m} c_p \frac{dT}{dx} + \sum_i h_i A_i (T_{s_i} - T_g) + Q_{r,rxn}$$

$$\rho V c_p \frac{dT_s}{dt} = \sum_i h_i A_i (T_{g_i} - T_s) + k \frac{dT_s}{dx} + \varepsilon F \sigma A (T_{s,opp}^4 - T_s^4) + Q_{e,rxn}$$

The complete SOFC model is solved simultaneously via constrained NLP using the **APMonitor** Modeling Language.

## Anode Steam Reforming Model



$$r_1 = A \exp \left( - \frac{E_a}{RT_{sa}} \right) p_{CH_4} \cdot Area$$

$$r_2 = k \left( X_{CO} X_{H_2O} - \frac{X_{H_2} X_{CO_2}}{K_{ps}} \right) \cdot Vol$$

$$\min_{x \in \Omega} J(x, u)$$

$$s.t. \dot{x} = f(x, u)$$

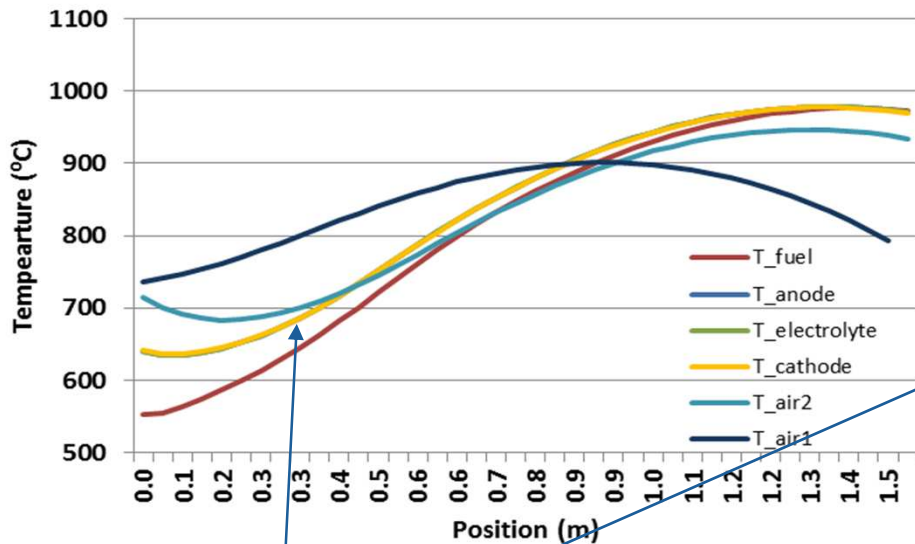
$$0 = g(x, u)$$

$$h(x) \geq 0$$

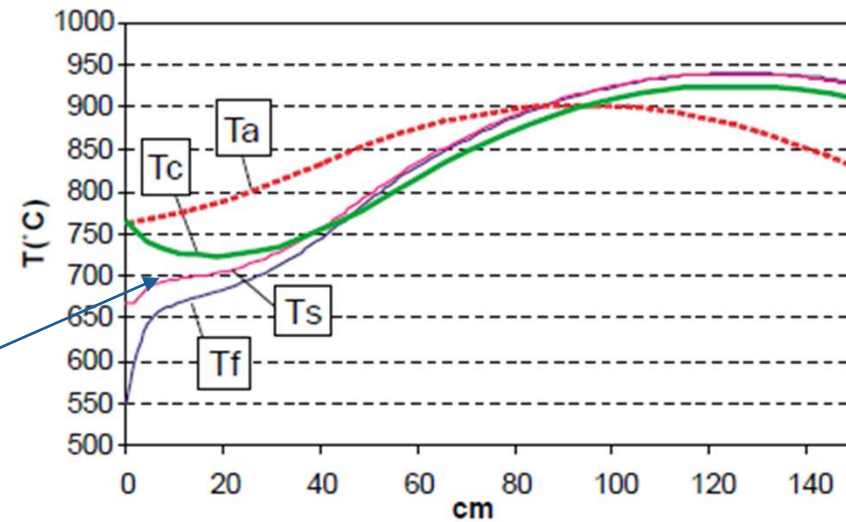
# SOFC Steady-State Model Validation

The tubular SOFC steady-state model is validated based upon experimental data and model data from standard practice (Campanari, 2004; Seume, 2009).

Model Results



Campanari Model



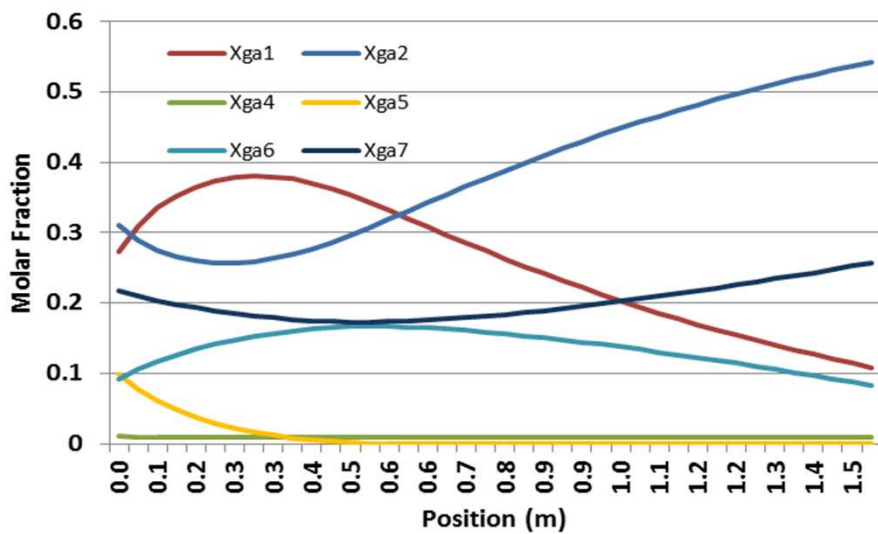
The mean absolute percentage (MAP) error is used to compare the models.

MAP for Electrolyte Temperature = 3.85%

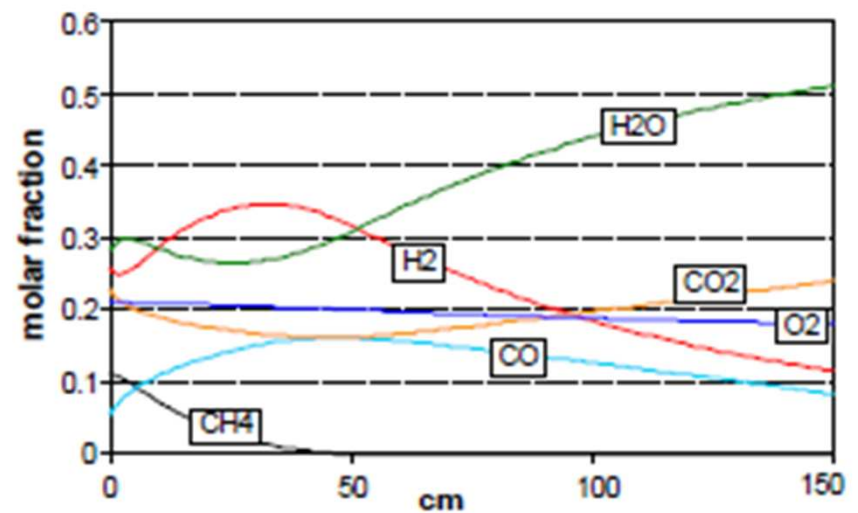
$$MAP = \frac{1}{n} \sum_t \left| \frac{A_t - P_t}{A_t} \right|$$

# SOFC Steady-State Model Validation

Model Results



Campanari Model

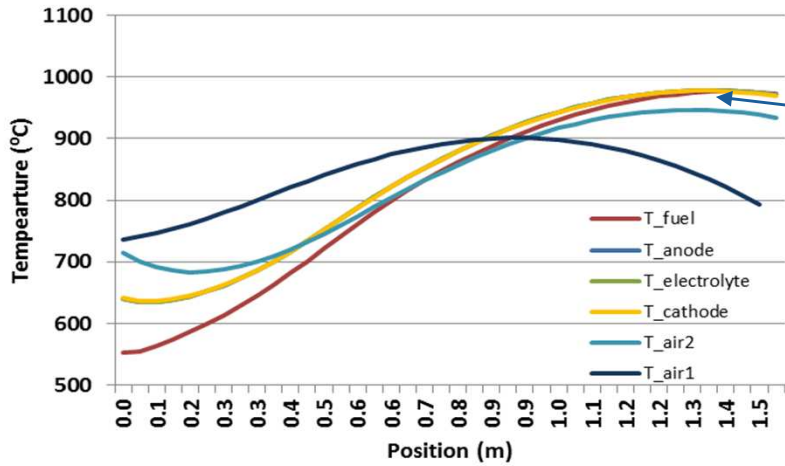


Comparison of the concentration profiles also indicates that the steady-state model matches well versus the standard models used for tubular, high-temperature SOFC modeling.

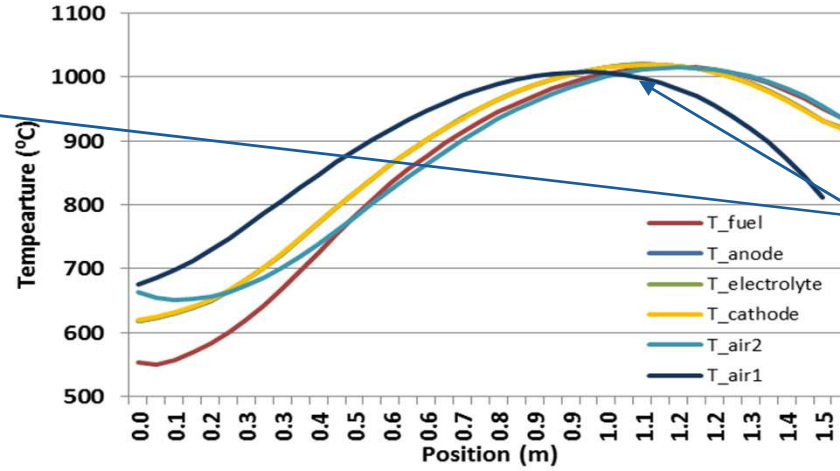
# SOFC Radiation Sensitivity

## Radiation Analysis for Plant B : Air channel radiation is significant

Without Radiation

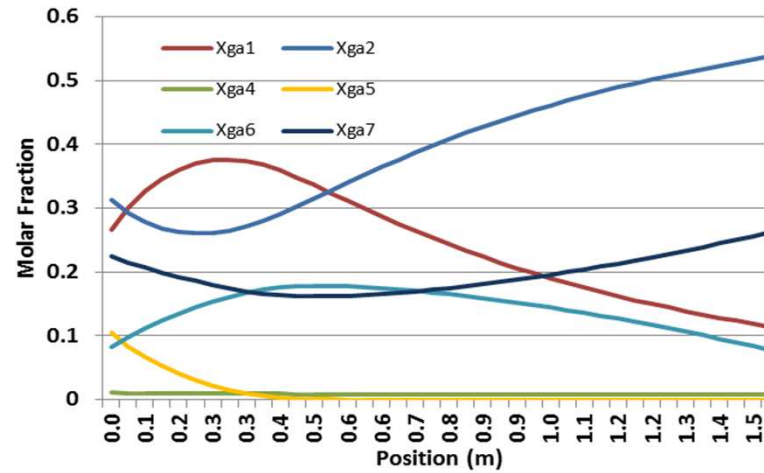
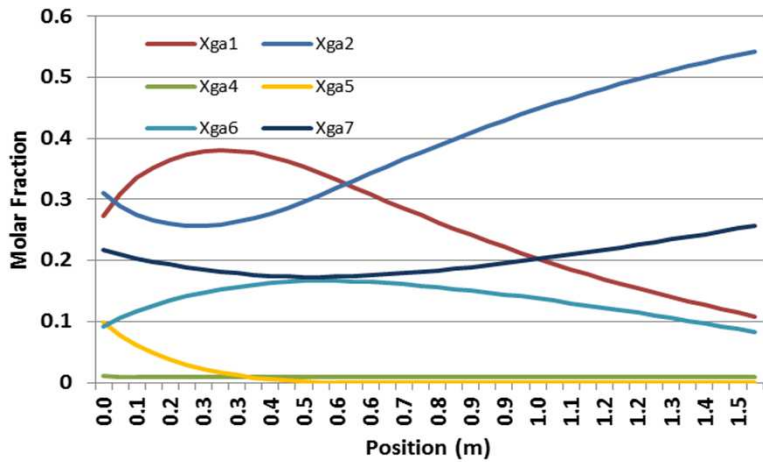


With Radiation



### Radiation Effects:

- Increased peak temperature
- Inlet air and solid PEN is closer in temperature
- Higher T gradients at outlet

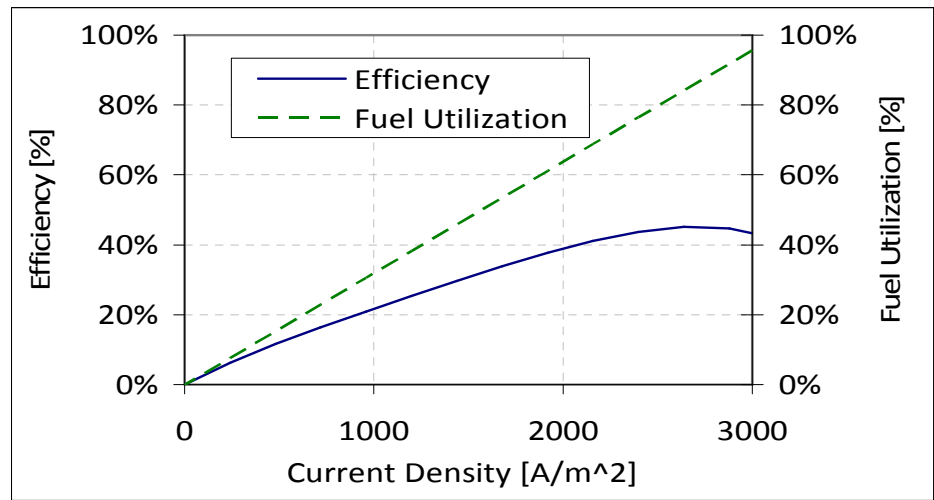
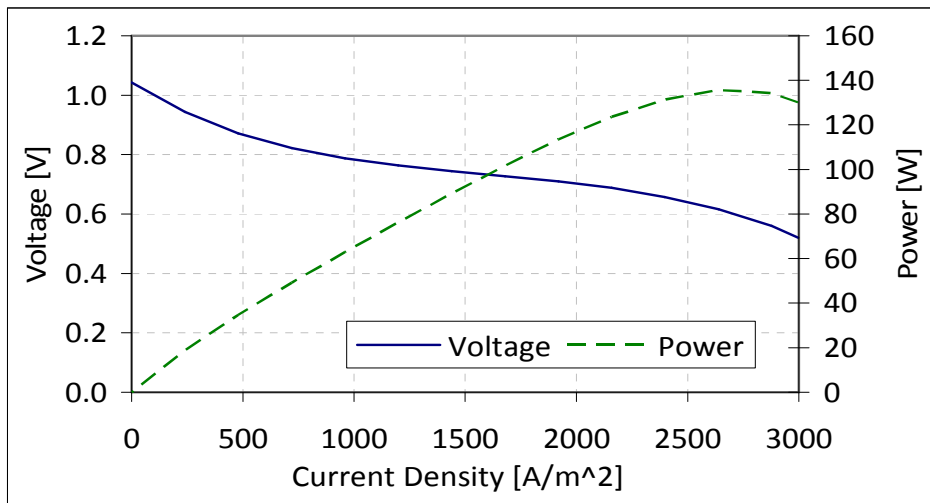


- Molar flow exhibits no noticeable change.

**Final Steady-State Model = Validated Campanari Model + Air Channel Radiation + Model Validation**

# SOFC Electrical Characterization

SS Electrical Characterization for Plant A: 120 kW, 1.05 bar

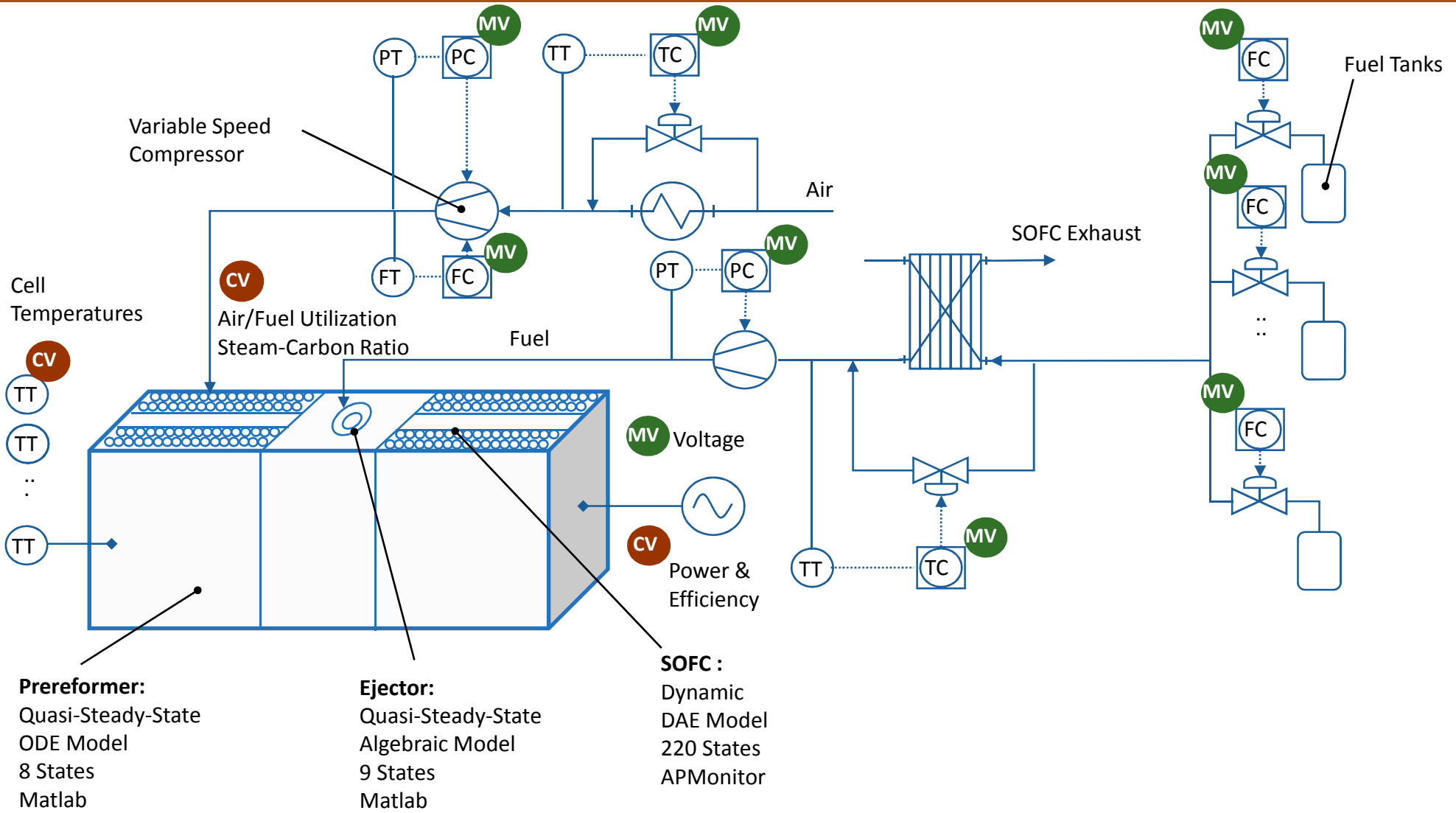


- LHV efficiencies are 45% and 38% for Plants A and B respectively - typical for 100-300 kW SOFC.
- Nominal efficiency is based upon provided inputs, not plant modeling.
- Fixed fuel flow rate condition

$$\eta = \frac{I \cdot V}{LHV_{H_2O} \cdot N_{H_2O,in} + LHV_{CO} \cdot N_{CO,in} + LHV_{CH_4} \cdot N_{CH_4,in}}$$

# SS and Dynamic Simulations of Fuel Cell Operation

# SOFC and Balance of Plant (BOP) System



Manipulated and controlled variables are chosen based upon the SOFC+BOP system

# Relevance of Controlled Variables

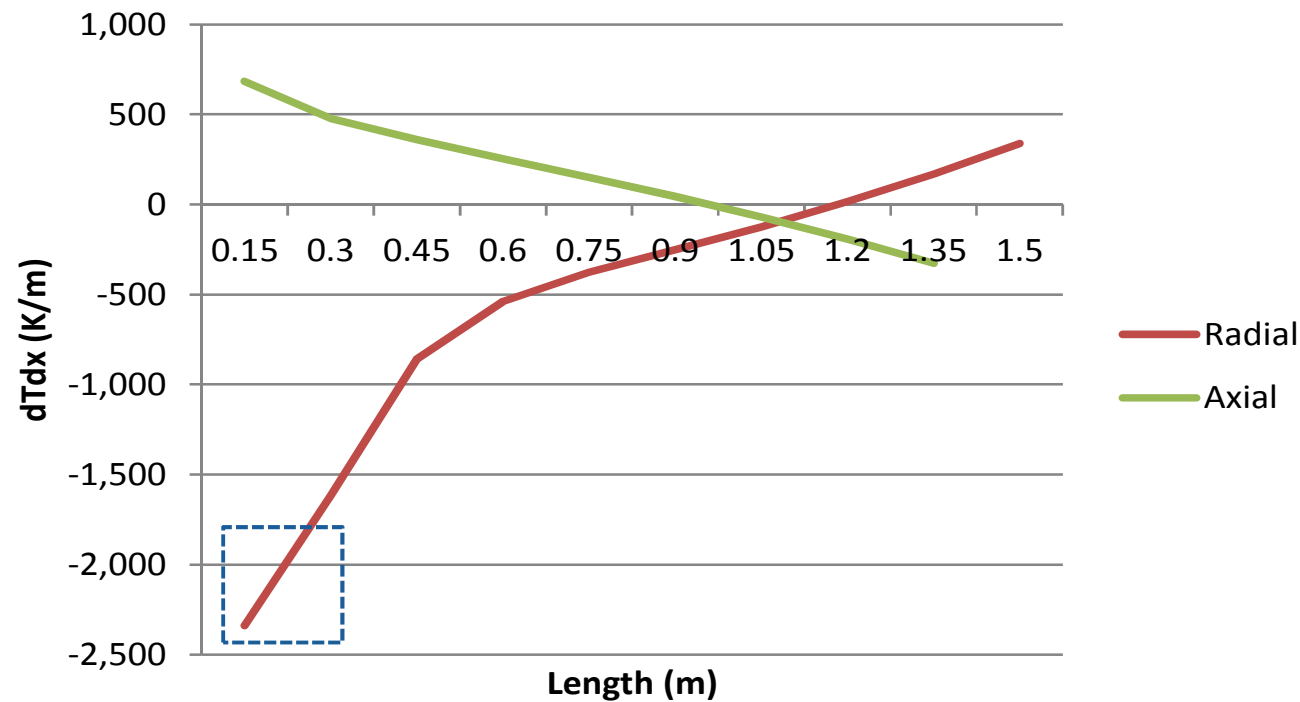
Objective or Risk	Controlled Variable
DC Power Delivery	Power (W) Efficiency (%)
Thermal Stress Minimization	Minimum Stack Temperature (K) Radial Thermal Gradient (K/m)
Avoid Catalyst Poisoning	Steam-to-Carbon Ratio
Avoid Air and Fuel Starvation	Air and Fuel Utilization (%)

Recent studies report that the minimum stack temperature and radial thermal gradient are responsible for the highest and second-highest thermal stress levels (Seume, 2009).



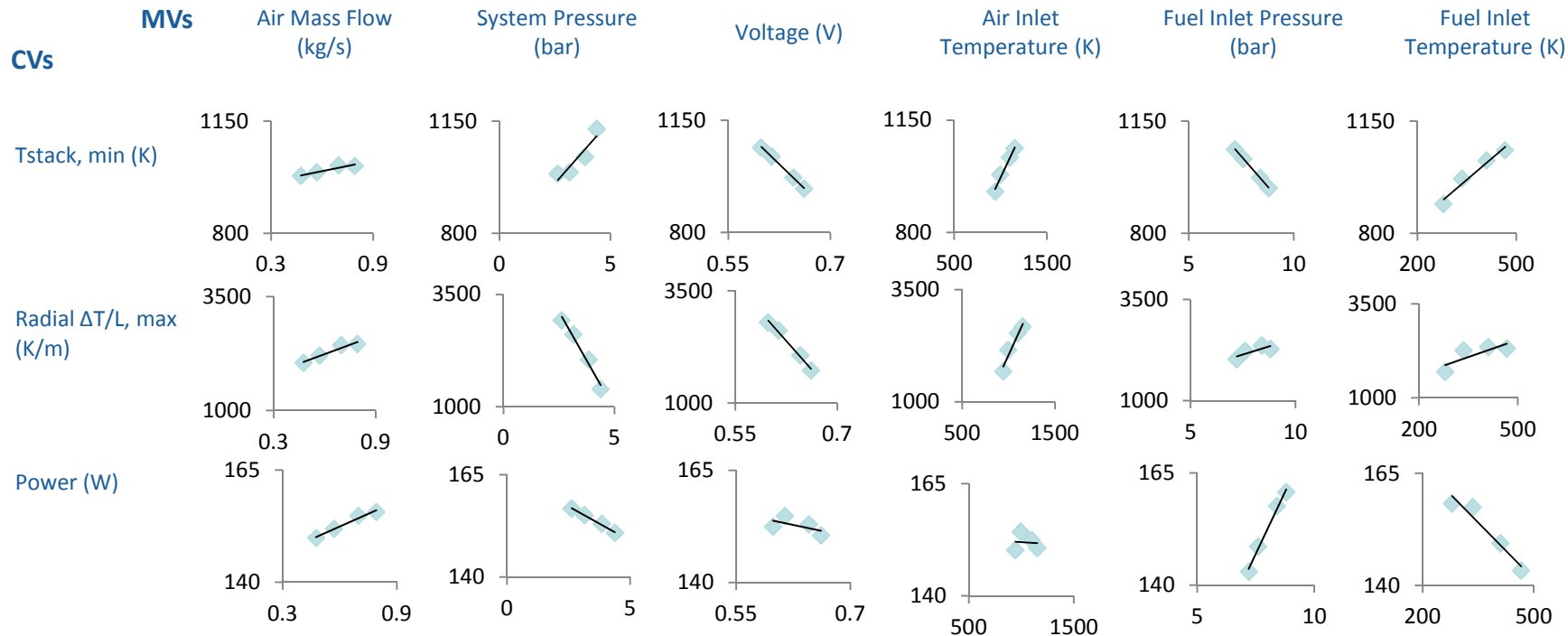
# Radial versus Axial Temperature Gradient

The radial gradient is negative near the fuel inlet placing the anode in tension. The radial gradient is several times the axial gradient.



*Simulation results agree with prior studies indicating that radial thermal gradients are most significant.*

# Variable Steady-State Gains

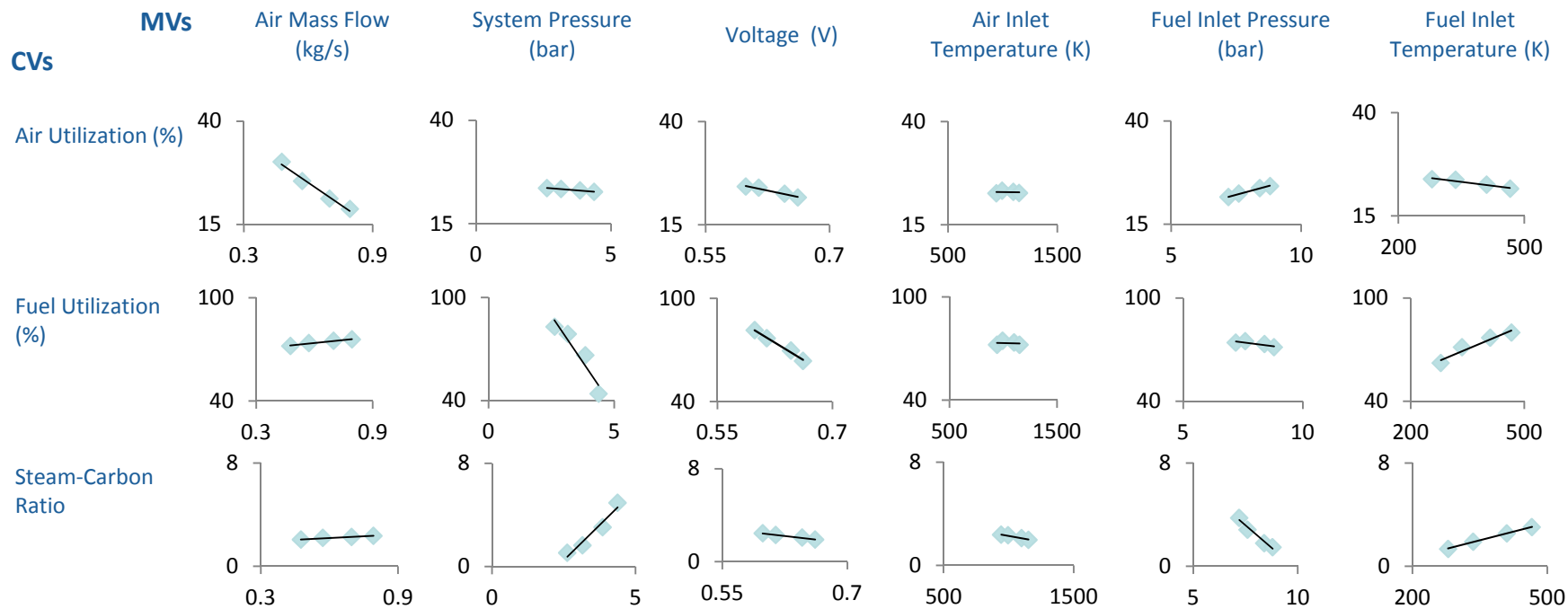


All scales are consistent for a given CV to compare slopes.

- Most MVs affect the minimum stack temperature.
- Air temperature and voltage affect the radial gradient significantly.
- Fuel pressure and temperature have most affect on power in this operating region.

*Manipulated variables (MVs) are adjusted 10-20% of nominal on both sides of the nominal value. Nominal is close to Plant B conditions.*

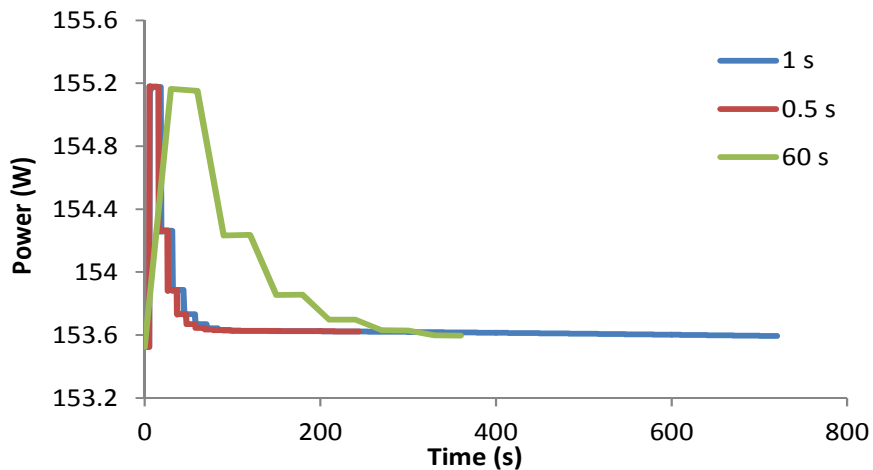
# Variable Steady-State Gains



- Air mass flow is a key MV for managing air utilization.
- Fuel temperature and system pressure manage fuel utilization.
- Fuel pressure and temperature and system pressure significantly affect the steam-to-carbon ratio.

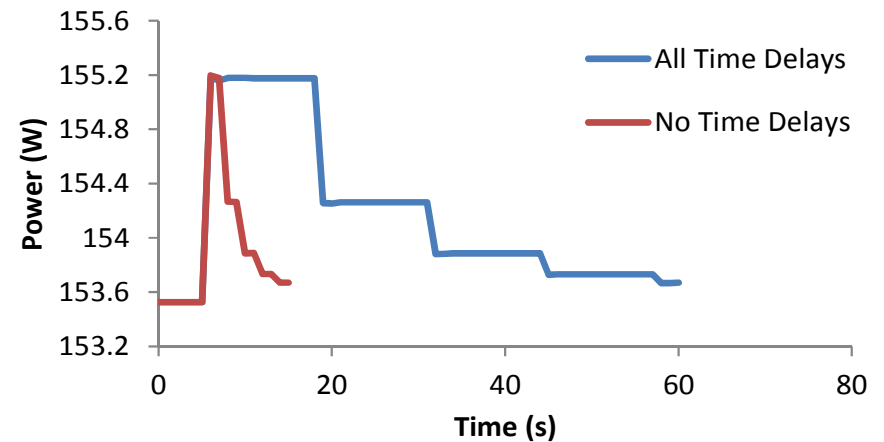
# Dynamic Simulation Design

## Simulation Time Discretization: Power Response to Voltage Step



- Decreasing time steps below 1 s yields little change in dynamic response.
- The QSS gas transport assumption is only valid to 1s time steps.

## Transport Time Delays

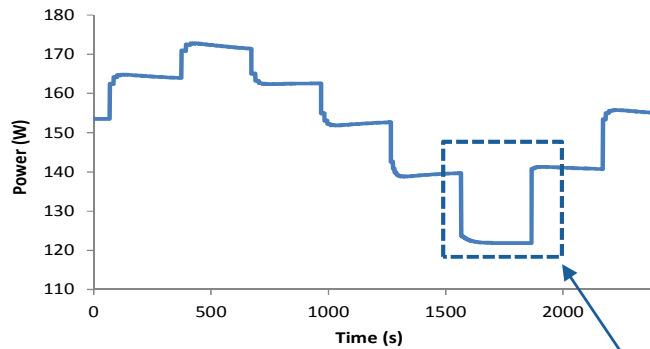


- Three transport time delays are added to the QSS gas transport models to improve dynamic accuracy.
- **Delays are important for sub-60 s response.**
- Delays are updated by mass flows

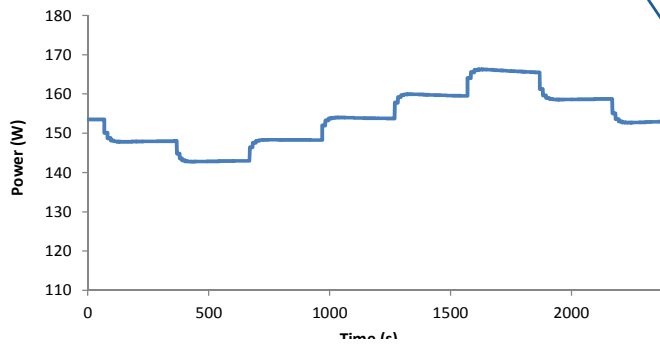
# Staircase Dynamic Simulations: Power Plots

MV:

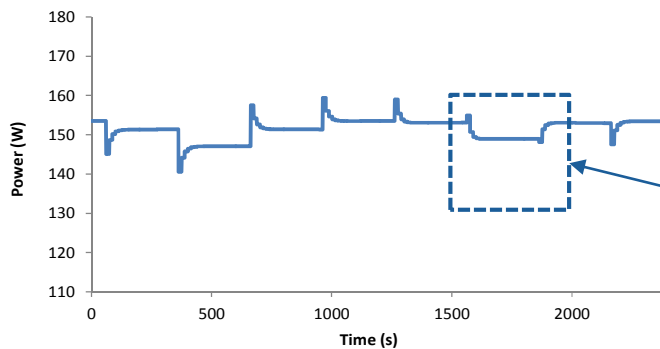
Fuel Pressure



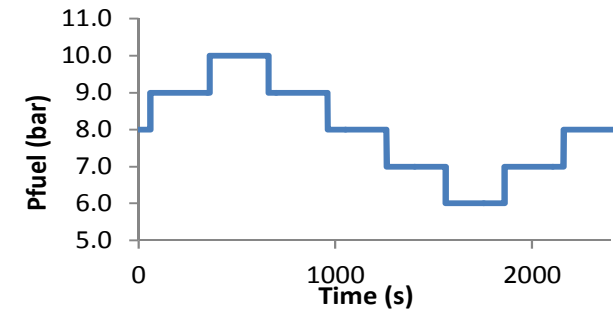
Fuel Temperature



Voltage



Example of staircase input:

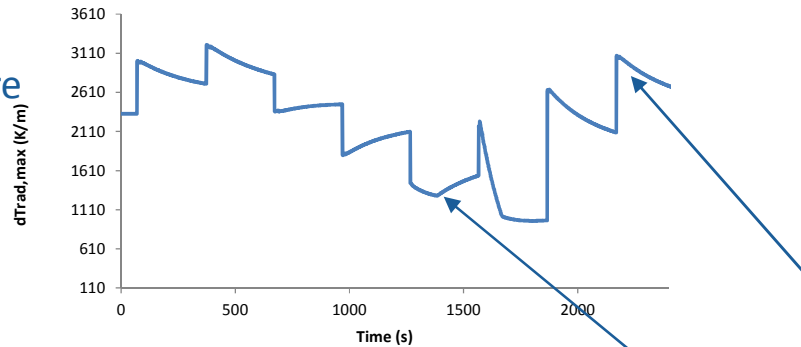


- Staircase tests are run over 5 minutes in response to MV steps over 1 s.
- Increasing gains further from the nominal illustrate non-linearity.
- Decreasing the voltage to 0.55 V reduces power output – crossed peak voltage and shows nonlinear V-P relationship.

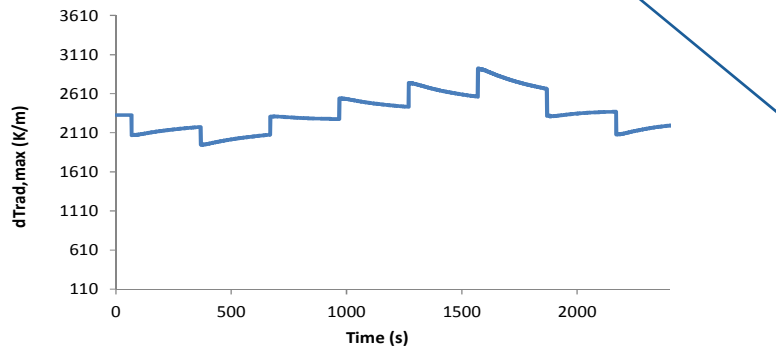
# Staircase Dynamic Simulations: Max Radial dTdr Plots

MV:

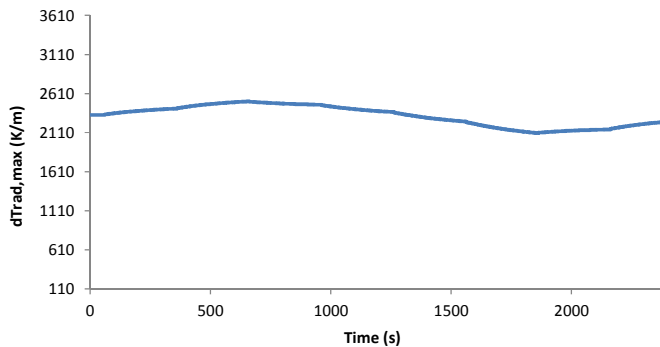
Fuel Pressure



Fuel Temperature



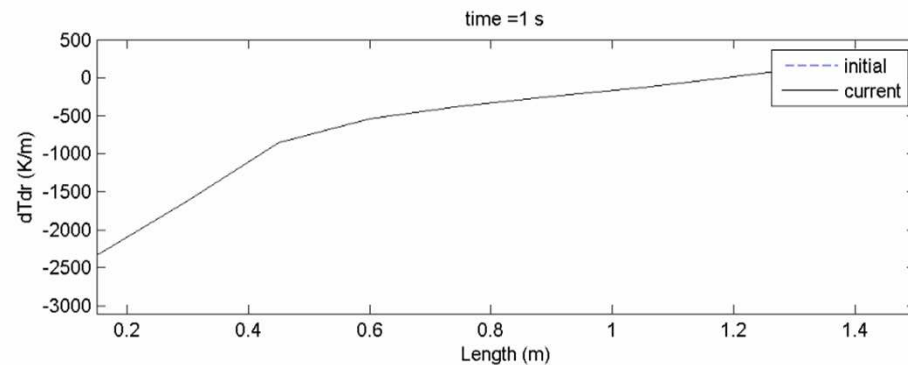
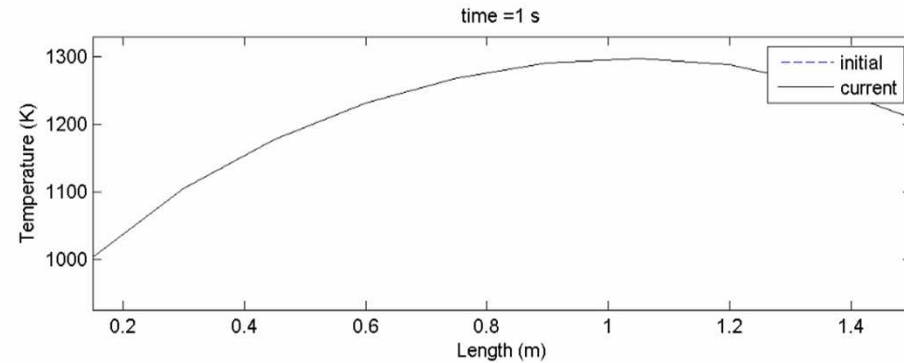
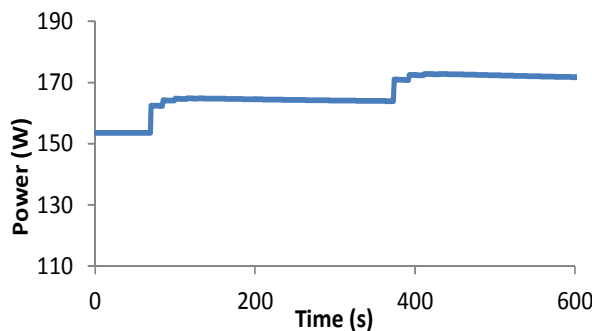
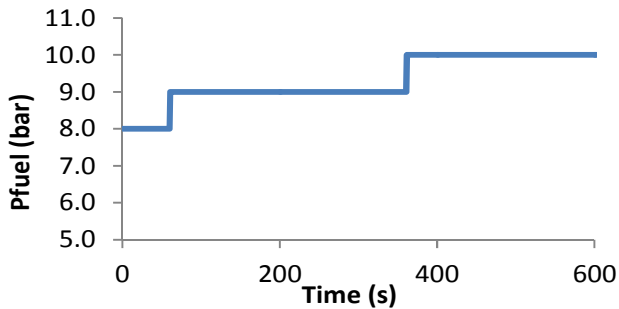
Air Mass Flow



- Numerator dynamics response is real and due to quickly changing anode chamber gas conditions.
- Discontinuous curves can result between step changes when location of max gradient changes.
- The maximum radial thermal gradient does not change quickly due to varying cathode-side conditions.

# Dynamic Evolution of the Temperature Profile

## Electrolyte Temperature and Radial Gradients



Open-Loop  
Pressure Step  
Increase

Fuel

Power Increase

-Lower Min Cell Temp.  
-Higher Max  $dT_{dr}$

Increased Thermal  
Stresses

*Minimum temperature and radial gradients undergo unique dynamics*

# Conclusions

- Modeling:

Distributed parameter modeling for SOFC is critical to accurately capture overall performance as well as local gradients and minimum temperatures – key reliability criteria.

- Simulation

- Radial thermal gradients may increase quickly in response to changing input conditions. Control algorithms should account for dynamics of minimum cell temperature and maximum radial gradients.
- Most properties have an initial rise time  $< 1$  min in response to 1 s input steps despite final settling times of hours. Control input intervals should be several times less than the rise time.



# Acknowledgments

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